

# NASA SDS Product Specification

# Level-2 Geocoded Pixel Offsets

L2\_GOFF

Rev -

JPL D-105010

November 9, 2023

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<u>01-Dec-2023</u> Date

<u>03-Dec-2023</u> Date

<u>29-Nov-2023</u> Date

<u>30-Nov-2023</u> Date

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### **EPDM ELECTRONIC SIGNATURES**

User-Group/Role	 Decision	Comments	Date
Cheng, Cecilia S (cecilia)-JPL Consumer/Project	 Approve		29-Nov-2023 11:31
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## ACKNOWLEDGEMENT

The research was carried out at the Jet Propulsion Laboratory, California Institute of Technology, under a contract with the National Aeronautics and Space Administration (80NM0018D0004).

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#### Document Change Log

Revision	Cover Date	Sections Changed	ECR #	Reason, ECR Title, LRS #*
Preliminary	March 04, 2022	All	N/A	New document
Working version (R3.1)	August 05, 2022	Front page, Sec 2.1	N/A	Updated NISAR ADT Lead; updated product dependency figure
Working version (R3.1)	August 05, 2022	Cover. TBD, TBC tables, Acronym List	N/A	Requested fixes. LRR067556
Working version (R3.2)	January 27, 2023	All	N/A	Revised for R3.2 release
Preliminary (R3.3)	June 6, 2023	All	N/A	Revised for R3.3 release URS CL #23-3138
Initial (R3.4)	November 9, 2023	Cover page, Sec. 1.3, Sec. 2.2, Sec. 3.2.2. Sec 5.2, 5.3, 5.4, 5.6		Modified document date and changed document revision; Updated reference to RSLC product specification and NISAR filename convention document; Removed reference and link to EPDM; Added reference to NISAR SDS ATBD; Modified Table 3.4 to reflect information in product XML specifications. Sec 5.2 Identification. Sec 5.3 Projection, Coordinates, FillValue. Sec 5.4 Processing Information. Sec 5.6 Geolocation Grid.
* Include the JF	PL Limited Release S	System (LRS) clearance n	umber for e	ach revision to be shared with foreign partners.

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## LIST OF TBC ITEMS

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Page	Section	Date / Release

### LIST OF TBD ITEMS

These items are to be completed when document is ready to enter configuration control.

Page	Section	Date / Release

#### INTRODUCTION 1

### 1.1 Purpose of Description

This document provides a specification of the NASA-ISRO Synthetic Aperture Radar (NISAR) L-SAR L2 Geocoded Pixel Offsets product to be generated by the NASA Science Data System (SDS) and provided to the Distributed Active Archive Center (DAAC). This data product is referenced by the short name L2\_GOFF.

### 1.2 Document Organization

Section 2 provides an overview of the product, including its purpose, and latency.

Section 3 provides the structure of the product, including granule definition, file organization, spatial resolution, temporal and spatial organization of the content, the size and data volume.

Section 4 provides qualitative descriptions of the information provided in the product.

Section 5 provides a detailed identification of the individual fields within the L2\_GOFF product, including for example their units, size, and coordinates.

Section 6 provides a description of the metadata cube representation.

Appendix A provides a listing of the acronyms used in this document.

### 1.3 Applicable and Reference Documents

Applicable documents levy requirements on areas addressed in this document. Reference documents are cited to provide additional information to readers. In case of conflict between the applicable documents and this document, the Project shall review the conflict to find the most effective resolution.

#### **Applicable Documents**

[AD1] NISAR NASA SDS Level 4 Requirements, JPL D-95655, Initial, Sep. 13, 2019 NISAR NASA SDS Algorithm Development Plan, JPL D-95678, Initial, [AD2] Sep. 12, 2019 [AD3] NISAR Science Data Management and Archive Plan, JPL D-80828, June 1, 2016 [AD4] NISAR Science Management Plan, JPL D-76340, Rev A, Aug. 14, 2018 [AD5] NISAR Calibration and Validation Plan, JPL D-102256, September. 2019 NISAR NASA SDS L4 Software Management Plan (SMP), JPL D-95656, [AD6] Rev A, Sep. 19, 2019

#### **Reference Documents**

- [RD1] NISAR NASA SDS Algorithm Theoretical Basis Document, JPL D-95677, Initial, Feb. 06, 2022.
- [RD2] EOSDIS Handbook, July 2016, retrieved from https://cdn.earthdata.nasa.gov/conduit/upload/5980/EOSDISHandbookWebFinaL2.pdf
- [RD3] NISAR SDS File Naming Conventions, JPL D-102255, Rev. A, Apr. 28, 2023.
- [RD4] NISAR L1\_RSLC Product Specification Document, JPL D-102268, R3.4, Oct. 23, 2023.
- [RD5] HDF5 documentation at https://portal.hdfgroup.org/display/HDF5/HDF5.
- [RD6] Eineder, M. (2003), Efficient simulation of SAR interferograms of large areas and of rugged terrain, IEEE Transactions on Geoscience and Remote Sensing, 41(6), 1415-1427.

The NISAR Level 1 science requirements are translated into requirements on the various spacecraft and instrument systems, including the requirements related to the processing system producing the L0-L2 products. These SDS requirements [AD1] fall into three general categories: resolution requirements, radiometric and spatial location accuracy requirements, and latency and throughput requirements.

## 2 PRODUCT OVERVIEW

### 2.1 Product Background

Each NASA SDS L0B-L2 LSAR product (Figure 2-1 and Table 2-1 Product Dependency) is distributed as a single Hierarchical Data Format version 5 (HDF5) [RD5] granule. All the metadata and imagery data are packaged in clearly defined sub-groups within the granule in compliance with the HDF5 specification. The NISAR product level definitions are given in **Error! Reference source not found.** 



Figure 2-1 Product Dependency

Product	Scope	Description	Granule Size
Radar Raw Science Telemetry (RRST)	Global	This L0A product is the raw downlinked data delivered to SDS	By downlinked files
Radar Raw Signal Data (RRSD)	Global	This L0B product is corrected, aligned radar pulse data derived from the RRST products and used for further processing	By radar observation, i.e., continuous data collected in a single radar mode
Calibration Raw Signal Data (CRSD)	Global	This L0B product contains instrument calibration data.	By radar data take, i.e., a sequence of observations for one radar-on period

#### Table 2-1. Key to Product Dependency Diagram

Product	Scope	Description	Granule Size
Range-Doppler Single Look Complex (RSLC)	Global	Used to generate all higher-level products	On pre-defined track/frame. High-resolution modes will have a high-res RSLC product and a background resolution RSLC product
Range-Doppler Nearest- Time Interferogram (RIFG)	Antarctica, Greenland, and selected mountain glaciers. Nearest pair in time and co- pol channels only.	Multi-looked interferogram in Range Doppler coordinates with geometrical phase (including topographic phase) removed and formed using high-resolution dense pixel offsets.	On pre-defined track/frame
Range-Doppler Nearest- Time Pixel Offsets (ROFF)	Antarctica, Greenland, and selected mountain glaciers. Nearest pair in time and co- pol channels only.	Unfiltered and unculled layers of pixel offsets in Range Doppler coordinates with different resolutions obtained from incoherent speckle tracking.	On pre-defined track/frame
Range-Doppler Nearest- Time Unwrapped Interferogram (RUNW)	Antarctica, Greenland, and selected mountain glaciers. Nearest pair in time and co- pol channels only.	Multi-looked, unwrapped differential interferogram in Range Doppler coordinates with geometrical phase (including topographic phase) removed.	On pre-defined track/frame

Product	Scope	Description	Granule Size
Geocoded SLC (GSLC)	Global and all channels.	Geocoded version of RSLC product using the MOE state vectors and a DEM.	On pre-defined track/frame
Geocoded Nearest-Time Pixel Offsets (GOFF)	Antarctica, Greenland, and selected mountain glaciers. Nearest pair in time and co-pol channels only.	Geocoded version of ROFF product using the MOE state vectors and a DEM.	On pre-defined track/frame

Product	Scope	Description	Granule Size
Geocoded Nearest-Time Unwrapped Interferogram (GUNW)	Global. Nearest pair in time and co-pol channels only.	Geocoded, multi-looked unwrapped differential Interferogram with geometrical phase (including topographic phase) removed. It contains a geocoded version of the wrapped interferogram and normalized interferometric correlation at a finer posting.	On pre-defined track/frame
Geocoded Polarimetric Covariance Matrix (GCOV)	Global and all channels. Single/Dual/Quad pol.	Geocoded, multi-looked polarimetric covariance matrix.	On pre-defined track/frame

#### Table 2-2 NISAR Data Level Descriptions defined by Science.

Data Level	Description
Level 0A	Unprocessed instrument data with communications artifacts removed, but without conditioning to reconstructed and reordered to represent the time- ordered sequence of samples from the instrument. May still contain bit errors and missing data that needs reconstruction.
Level 0B	Reconstructed, unprocessed instrument data at original resolution, time ordered, all communications artifacts removed.
Level 1	Processed instrument data, focused to full resolution complex images, time referenced and annotated with ancillary information, including radiometric and relevant geometric calibration coefficients and georeferencing parameters (i.e. platform ephemeris) computed and appended, in natural radar coordinates.
Level 2 Category 1	Derived radar-specific parameters at the same or reduced resolution as Level 1 imagery, but resampled and geocoded to a geographic or ellipsoidal grid.
Level 2 Category 2	Derived radar-specific parameters at reduced resolution, in original Level 1 coordinates.
Level 3	Geophysical parameters derived from Level 1 or 2 data that have been spatially and/or temporally re-sampled to a global grid.

### 2.2 L2\_GOFF Overview

The L2\_GOFF product is a Level 2 Category 1 product derived from the L1\_ROFF product by using a Digital Elevation Model (DEM) and projecting the Range Doppler pixel offsets layers into the UTM/Polar Stereographic system (Appendix B: Geocoded Products Grids).

The L2\_GOFF product contains individual binary raster layers representing the pixel offset shifts between a pair of coarsely coregistered L1\_RSLC granules. The spacing, the window size, and

the search radius used to generate the pixel offsets layers in the Range Doppler geometry are summarized in Table 2-3 to Table 2-6 organized by slant (e.g., 40 MHz single pol) and area of observation. Pixel offsets layers within a L2 GOFF granule share the same starting pixel and are referenced to geographic coordinates [RD1]. Pixel offset layers are distributed without performing any conventional post-processing operation i.e., layers might contain offsets outliers and are not low pass filtered to reduce noise in the data [RD1].

The L2\_GOFF product is primarily meant for cryosphere applications and is only generated for L-SAR acquisitions over Antarctica, Greenland, and selected mountain glaciers.

Layer**	Range Bandwidth (MHz)	Sample spacing in slant range (pixels)	Sample spacing in along-track (pixels)	Window size in slant-range (pixels)	Window size in along-track (pixels)	Search radius in slant range (pixels)	Search radius in along-track (pixels)
IL1_80IS	80	30	15	64	32	64	33
IL2_80IS	80	30	15	96	64	64	33
IL3_80IS	80	30	15	196	128	8	8

Table 2-3. Pixel offset layers: 80 MHz, Antarctica, and Greenland

IL stands for incoherent speckle tracking layer

#### Table 2-4. Pixel offset layers: 40 MHz, Antarctica, and Greenland

Layer*	Range Bandwidth (MHz)	Sample spacing in slant range (pixels)	Sample spacing in along-track (pixels)	Window size in slant range(pixels)	Window size in along- track (pixels)	Search radius in slant range (pixels)	Search radius in along-track (pixels)
IL1_40IS	40	15	15	32	32	8	8
IL2_40IS	40	15	15	64	64	8	8
IL3_40IS	40	15	15	128	128	8	8

IL stands for incoherent speckle tracking layer

#### Table 2-5. Pixel offset layers: 20 MHz, mountain glaciers

Layer**	Range Bandwidth (MHz)	Sample spacing in slant range (pixels)	Sample spacing along-track (pixels)	Widow size in slant range (pixels)	Window size in along- track (pixels)	Search radius in slant range (pixels)	Search radius in along-track (pixels)
IL1_20MG	20	8	15	32	32	16	32
IL2_20MG	20	8	15	32	64	16	32
IL3_20MG	20	8	15	64	128	16	32

IL stands for incoherent speckle tracking layer

#### Table 2-6. Pixel offset layers: 40 MHz, mountain glaciers

Layer**	Range Bandwidth (MHz)	Sample spacing in slant range (pixels)	Sample spacing along-track (pixels)	Window size in slant range (pixels)	Window size in along- track (pixels)	Search radius in slant range (pixels)	Search radius in along-track (pixels)
IL1_40MG	40	15	15	32	32	32	32
IL2_40MG	40	15	15	64	64	32	32
IL3_40MG	40	15	15	128	128	32	32

IL stands for incoherent speckle tracking layer

The structure of the L2\_GOFF product is described in Section 4. The details of the data elements are given in Section 5. Metadata cubes are discussed in Section 6.

## **3 PRODUCT ORGANIZATION**

### 3.1 File Format

All NISAR standard products are in the Hierarchical Data Format version 5 (HDF5 [RD5]). HDF5 is a general-purpose file format and programming library for storing scientific data. The National Center for Supercomputing Applications (NCSA) at the University of Illinois developed HDF to help scientists share data more easily. Use of the HDF library enables users to read HDF files regardless of the underlying computing environments. HDF files are equally accessible in Fortran, C/C++, and other high-level computation packages such as IDL, MATLAB or Python.

The HDF Group, a spin-off organization of the NCSA, is responsible for development and maintenance of HDF. Users should reference The HDF Group website at <a href="https://portal.hdfgroup.org/display/HDF5/HDF5">https://portal.hdfgroup.org/display/HDF5/HDF5</a> [RD5] to download HDF software and documentation.

HDF5 represents a significant departure from the conventions of previous versions of HDF. The changes that appear in HDF5 provide flexibility to overcome many of the limitations of previous releases. The basic building blocks have been largely redefined and are more powerful but less numerous. The key concepts of the HDF5 Abstract Data Model are Files, Groups, Datasets, Datatypes, Attributes and Property Lists. The following sections provide a brief description of each of these key HDF5 concepts.

#### 3.1.1 HDF5 File

A File is the abstract representation of a physical data file. Files are containers for HDF5 Objects. These Objects include Groups, Datasets, and Datatypes.

#### 3.1.2 HDF5 Group

Groups provide a means to organize the HDF5 Objects in HDF5 Files. Groups are containers for other Objects, including Datasets, named Datatypes and other Groups. In that sense, groups are analogous to directories that are used to categorize and classify files in standard operating systems.

The notation for files is identical to the notation used for Unix directories. The root Group is "/". A Group contained in root might be called "/myGroup." Like Unix directories, Objects appear in Groups through "links". Thus, the same Object can simultaneously be in multiple Groups.

#### 3.1.3 HDF5 Dataset

The Dataset is the HDF5 component that stores user data. Each Dataset associates with a Dataspace that describes the data dimensions, as well as a Datatype that describes the basic unit of storage element. A Dataset can also have Attributes.

#### 3.1.4 HDF5 Datatype

A Datatype describes a unit of data storage for Datasets and Attributes. Datatypes are subdivided into Atomic and Composite Types.

Atomic Datatypes are analogous to simple basic types in most programming languages. HDF5 Atomic Datatypes include Time, Bitfield, String, Reference, Opaque, Integer, and Float. Each atomic type has a specific set of properties. Examples of the properties associated with Atomic Datatypes are:

- Integers are assigned size, precision, offset, pad byte order, and are designated as signed or unsigned.
- Strings can be fixed or variable length and may or may not be null-terminated.
- References are constructs within HDF5 Files that point to other HDF5 Objects in the same file.

HDF5 provides a large set of predefined Atomic Datatypes. Table 3-1 lists the Atomic Datatypes that are used in NISAR data products.

HDF5 Atomic	
Datatypes	Description
H5T_STD_U8LE	unsigned, 8-bit, little-endian integer
H5T_STD_U16LE	unsigned, 16-bit, little-endian integer
H5T_STD_U32LE	unsigned, 32-bit, little-endian integer
H5T_STD_U64LE	unsigned, 64-bit, little-endian integer
H5T_STD_I8LE	signed, 8-bit, little-endian integer
H5T_STD_I16LE	signed, 16-bit, little-endian integer
H5T_STD_I32LE	signed, 32-bit, little-endian integer
H5T_STD_I64LE	signed, 64-bit, little-endian integer
H5T_IEEE_F32LE	32-bit, little-endian, IEEE floating point
H5T_IEEE_F64LE	64-bit, little-endian, IEEE floating point
H5T_C_S1	character string made up of one or more bytes

Table 3-1. HDF5 Atomic Datatypes

Derived Datatypes are user-defined variants of predefined Atomic Datatypes where the data organization has been modified at the bit-level. Derived data types are particularly useful for representing custom N-bit integers and floating-point numbers.

Composite Datatypes incorporate sets of Atomic datatypes. Composite Datatypes include Array, Enumeration, Variable Length and Compound.

• The Array Datatype defines a multi-dimensional array that can be accessed atomically.

- Variable Length presents a 1-D array element of variable length. Variable Length Datatypes are useful as building blocks of ragged arrays.
- Compound Datatypes are composed of named fields, each of which may be dissimilar Datatypes. Compound Datatypes are conceptually equivalent to structures in the C programming language.

Named Datatypes are explicitly stored as Objects within an HDF5 File. Named Datatypes provide a means to share Datatypes among Objects. Datatypes that are not explicitly stored as Named Datatypes are stored implicitly. They are stored separately for each Dataset or Attribute they describe.

NISAR products employ the following Derived and Compound Datatypes.

Description	Comments
16-bit little-endian floating point	"binary16" half precision type in IEEE 754-2008 standard. Matches numpy.float16 type in Python. We will refer to this type as H5T_IEEE_F16LE or Float16 in our documents.
H5T_COMPOUND {     16-bit little-endian floating-point "r";     16-bit little-endian floating-point "i"; }	Complex numbers made up of two half precision floating point numbers. We will refer to this type as H5T_CPX_F16LE or CFloat16 in our documents.
H5T_COMPOUND { 32-bit little-endian floating-point "r"; 32-bit little-endian floating-point "i"; }	Complex numbers made of two single precision floating point numbers. We will refer to this type as H5T_CPX_F32LE or CFloat32 in our documents.
H5T_COMPOUND { 64-bit little-endian floating-point "r"; 64-bit little-endian floating-point "i"; }	Complex numbers made of two double precision floating point numbers. We will refer to this type as H5T_CPX_F64LE or CFloat64 in our documents.

#### Table 3-2 NISAR HDF5 Derived and Compound Datatypes

#### 3.1.5 HDF5 Attribute

An Attribute is a small aggregate of data that describes Groups or Datasets. Like Datasets, Attributes are also associated with a particular Dataspace and Datatype. Attributes cannot be subsetted or extended. Attributes themselves cannot have Attributes.

### 3.2 NISAR File Organization

#### 3.2.1 Groups

All NISAR HDF5 files are organized as groups with no actual data at the root("/") level. Table 3-3 shows the general layout of the HDF5 files that are generated by the NISAR Science Data System. All data are organized under "/science" with data from the L-SAR and S-SAR instruments separated into their own groups.

Table 3-3	Groun	organization	at the to	n level	of a	NISAR	HDF5	File
1 aute 3-3	Oroup	organization	at the to	piever	01 a	MISAK	IIDF5	LUG

Group Name	Description
/science/LSAR	All science data from the L-SAR instrument is organized under this group
/science/SSAR	All science data from the S-SAR instrument is organized under this group
/science/LSAR/identification	File level metadata for cataloging, archiving the granule

In the nominal baseline, L-SAR and S-SAR data will not appear in the same granule, even if they cover the same geographic area. Data structure described below the primary groups ("/science/LSAR" for L-SAR and "/science/SSAR" for S-SAR) will be the same for L-SAR and S-SAR products. The rest of the document from this point on describes the layout of the product containing L-SAR data. The specification for equivalent S-SAR data products is expected to be the same except for the substitution of "LSAR" by "SSAR" in the dataset paths in the HDF5 granule.

#### 3.2.2 File Level Metadata

Global metadata at the file level are currently given as Global Attributes shown in Table 3-4.

Metadata regarding the data in the particular granule are given in "/science/LSAR/identification" for L- or S-SAR. These data are described further in Sec 4.2 and Sec 5.2.

Attribute	Format	Description	Value
Conventions	string	NetCDF-4 conventions adopted in this product. This attribute should be set to CF-1.8 to indicate that the group is compliant with the Climate and Forecast NetCDF conventions.	CF-1.7
title	string	Product title.	NISAR L2_GOFF Product
institution	string	Name of producing agency.	NASA JPL
mission_name	string	Mission name.	NISAR

Table 3-4	Global	attributes	of L2_	GOFF
-----------	--------	------------	--------	------

reference_document	string	Name and version of Product Description Document to use as reference for product.	D-105010 NISAR NASA SDS Product Specification L2 Geocoded Pixel Offsets
contact	string	Contact information for producer of product.	nisar-sds-ops@jpl.nasa.gov

#### 3.2.3 Variable Metadata (HDF5 Attributes)

NISAR standards incorporate additional metadata that describe each HDF5 Dataset within the HDF5 file. Each of these metadata elements appear in an HDF5 Attribute that is directly associated with the HDF5 Dataset. Wherever possible, these HDF5 Attributes employ names that conform to the Climate and Forecast (CF) conventions.

Table 3-5 lists the CF names for the HDF5 Attributes that NISAR products typically employ.

Attribute	Description
_FillValue	The value used to represent missing or undefined data. (Before applying
	add_offset and scale_factor).
add_offset	If present this value should be added to each data element after it is read.
	If both scale_factor and add_offset attributes are present, the data are
	first scaled before the offset is added.
scale_factor	If present, the data are to be multiplied by the value after they are read. If
	both scale_factor and add_offset attributes are present, the data are first
	scaled before the offset is added.
comment	Miscellaneous information about the data or the methods to generate it.
coordinates	Coordinate variables associated with the variable. The basename of the
	coordinate variable is used in this representation and group scoping rules
	for CF conventions apply.
long_name	A descriptive variable name that indicates its content.
quality_flag	Names of variable quality flag(s) that are associated with this variable to
	indicate its quality.
units	Unit of data after applying offset (add_offset) and scale_factor.
valid_max	Maximum theoretical value of variable before applying scale_factor and
	add_offset (not necessarily the same as maximum value of actual data)
valid_min	Minimum theoretical value of variable before applying scale_factor and
	add_offset (not necessarily the same as minimum value of actual data)

Table 3-5 Common va	riable	attributes	in	HDF5	file.
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Some HDF5 datasets are populates with statistical attributes. Table 3-6 and Table 3-7 describe the statistical attributes added to real- and complex-valued HDF5 datasets, respectively. The list of real-valued HDF5 datasets for the standard L2\_GOFF product is given in Table 3-8.

Attribute	Description
min_value	Minimum value of real-valued HDF5 dataset
mean_value	Mean value of real-valued HDF5 dataset
max_value	Maximum value of real-valued HDF5 dataset
sample_standard_deviation	Sample standard deviation of real-valued HDF5 dataset

Table 3-6 Statistical attributes for real-valued HDF5 datasets.

#### Table 3-7 Statistical attributes for complex-valued HDF5 datasets.

Attribute	Description
min_real_value	Minimum value of the real part of a complex-valued HDF5 dataset
mean_real_value	Mean value of the real part of a complex-valued dataset HDF5 dataset
max_real_value	Maximum value of the real part of a complex-valued HDF5 dataset
sample_standard_deviation_real	Sample standard deviation of the real part of a complex- valued HDF5 dataset
min_imag_value	Minimum value of the imaginary part of a complex-valued HDF5 dataset
mean_imag_value	Mean value of the imaginary part of a complex-valued HDF5 dataset
max_image_value	Max value of the imaginary part of a complex-valued HDF5 dataset
sample_standard_deviation_imag	Sample standard deviation of the imaginary part of a complex-valued HDF5 dataset

Table 3-8 L2\_GOFF HDF5 datasets populated with statistical attributes.

Attribute	HDF5 Datasets	Dataset type
/science/LSAR/GOFF/ grids/frequencyA/pixelOffsets/ HH/layer1/	slantRangeOffset alongTrackOffset alongTrackOffsetVariance slantRangeOffsetVariance crossOffsetVariance correlationSurfacePeak snr	Real-valued
/science/LSAR/GOFF/ grids/frequencyA/pixelOffsets/ VV/layer1/	slantRangeOffset alongTrackOffset alongTrackOffsetVariance slantRangeOffsetVariance crossOffsetVariance correlationSurfacePeak snr	Real-valued

/science/LSAR/GOFF/ grids/frequencyA/pixelOffsets/ HH/layer2/	slantRangeOffset alongTrackOffset alongTrackOffsetVariance slantRangeOffsetVariance crossOffsetVariance correlationSurfacePeak snr	Real-valued
/science/LSAR/GOFF/ grids/frequencyA/pixelOffsets/ VV/layer2/	slantRangeOffset alongTrackOffset alongTrackOffsetVariance slantRangeOffsetVariance crossOffsetVariance correlationSurfacePeak snr	Real-valued
/science/LSAR/GOFF/ grids/frequencyA/pixelOffsets/ HH/layer3/	slantRangeOffset alongTrackOffset alongTrackOffsetVariance slantRangeOffsetVariance crossOffsetVariance correlationSurfacePeak snr	Real-valued
/science/LSAR/GOFF/ grids/frequencyA/pixelOffsets/ VV/layer3/	slantRangeOffset alongTrackOffset alongTrackOffsetVariance slantRangeOffsetVariance crossOffsetVariance correlationSurfacePeak snr	Real-valued

### 3.3 Granule Definition

NISAR L2\_GOFF granules will conform to the Tiling Scheme being developed for the mission and are expected to have a ground footprint of approximately 240 km x 240 km except for 80 MHz data which cover half of the swath in range direction.

### 3.4 File Naming Convention

NISAR L2\_GOFF Granule names will conform to the SDS L-SAR Product File Naming Conventions [RD3].

### 3.5 Temporal Organization

Temporal organization is not specifically applicable to the L2\_GOFF product.

### 3.6 Spatial Organization

The L2 data are arranged on a uniformly spaced, North-up and West-left grid – i.e., decreasing North or Y coordinate in the row direction and increasing East or X coordinate in the column direction following the row-major order convention of representing 2D raster arrays. Pixel-is-area convention (see Appendix B: Geocoded Product Grids) is used to tag the raster layers with coordinate information.

### 3.7 Spatial Sampling and Resolution

Some salient features of the output grid for L2\_GOFF products are:

1. The top-left corner of the top-left pixel will correspond to the same geo-graphic coordinate for all the pixel offsets layers in a L-SAR L2\_GOFF product.

#### 3.7.1 Mosaicking

The spatial sampling of the output grid has been designed to facilitate along-track mosaicking of contiguous L2\_GOFF product granules if the user desires. See Appendix B: Geocoded Product Grids for details on the common output grid used for all L2 products.

Note that L2\_GOFF products generated from L1\_RSLC products with different central frequencies cannot be mosaicked for applications that expect phase continuity.

#### 3.7.2 Partially compressed SLC data

Partially compressed data in L1\_RSLC files will not be used to produce L2\_GOFF products.

## 4 LEVEL 2 GEOCODED PIXEL OFFSET PRODUCT

In this section, we briefly describe the layout of L2\_GOFF data and associated metadata within the NISAR HDF5 file. Detailed description of Group and Dataset names can be found in Section 5. In this section, we focus on the organization of L-SAR instrument data within the file under the Group name "/science/LSAR".

### 4.1 Shapes and Dimensions of Data

Information on the shapes and dimensions of the data items in various data tables are described as part of the metadata (Sec **Error! Reference source not found.**). This information is useful both as part of the product identification and for setting up further processing, i.e., dimensioning arrays.

### 4.2 Product Identification

Information needed to identify this product is given under the Group "/science/LSAR/identification" (Sec **Error! Reference source not found.**). This includes information such as orbit number, cycle number, track-frame number, acquisition times, a polygon representing the bounding box of the included imagery in geographic coordinates, and product version.

### 4.3 Radar Imagery

The imagery layers of the L2\_GOFF product are organized by center frequency under the group "/science/LSAR/GOFF/grids/frequencyA". Pixel offset layers are generated only from the main imaging band (frequencyA). The "frequencyA" group is further organized by polarization (TxRx) and each polarization group (e.g., HH) is further organized in distinct groups for each offset layer. For example, the dataset

"/science/LSAR/GOFF/grids/frequencyA/pixelOffsets/HH/layer1/slantRangeOffset" correspond to the first layer of slant range pixel offsets (i.e., IL1) obtained with the parameters described in Table 2-3 to Table 3-6 for polarization combination HH and center frequency frequencyA.

The details of the data elements are given in Section **Error! Reference source not found.**. The resolution of data elements is discussed in Section 2.2.

### 4.4 Radar Metadata

The *metadata* group under "/science/LSAR/GOFF/metadata" includes a list of miscellaneous metadata needed to interpret the imagery (e.g., layers of slant range and along-track pixel offsets) included in the L2\_GOFF product.

#### 4.4.1 Processing Information

The *processingInformation* includes the processing parameters used to generate the L2\_GOFF product. This group also include a list of the used algorithms, and the inputs granules and files used to produce L2\_GOFF. For a complete description of this group, refer to Section 5.4.

#### 4.4.1.1 Parameters

The *parameters* subgroup ("/science/LSAR/GOFF/metadata/processingInformation/parameters") is further organized in five subgroups:

- 1. *common*: organized by frequency, and including the parameters derived by combining the information from the reference and secondary RSLC such as the Doppler Centroid and the Doppler bandwidth
- 2. *reference*: including the reference terrain height of the reference RSLC and Boolean flags to indicate if the RSLC is the results of mixed mode processing and if RFI correction has been applied. This subgroup is further organized by frequency and includes some relevant parameters of the reference RSLC such as the slant range and zero Doppler time spacings, the slant range and the azimuth bandwidths, and the Doppler centroid.
- 3. *secondary*: this subgroup follows the same organization of *reference* but includes the corresponding metadata for the secondary RSLC.
- 4. *pixelOffsets*: including the parameters used to generate the individual layers of dense pixel offsets in the radar geometry. This group is further organized by frequency. The subgroup *frequencyA* contains the offsets parameter common to each layer of offsets i.e., the offset spacings in slant range and along-track direction, the correlation surface oversampling factor. The offsets parameters specific for each offset layer are further organized in the *layer* subgroups. Each *layer* subgroup contains the along-track and slant range window and search window sizes used to generate the pixel offsets for that specific layer.
- 5. *geocoding:* including a set of Boolean flags indicating the corrections that have been applied while geocoding the pixel offsets layers from radar to geographical coordinates i.e., wet and dry troposphere correction, slant range and azimuth ionosphere corrections.

The *parameters* subgroup also contains a field called *runConfigurationContents* which included the content of the run configuration file with all the options and the input files used for processing.

#### 4.4.1.2 Algorithms

The *algorithms* subgroup ("/science/LSAR/GOFF/metadata/processingInformation/algorithms") includes the name and the version of the software used to generate the product. The subgroup is further organized by the processing step used to generate the L2\_GOFF product:

- 1. *coregistration*: including the algorithms used to perform the coarse and fine coregistration of the reference and secondary RSLCs (e.g., geometry coregistration, cross-correlation algorithm).
- 2. *crossCorrelation*: further organized by offset layer and including the cross-correlation algorithm used to generate each individual layer of pixel offset.
- 3. *geocoding*: including the algorithms used to perform the geocoding of the pixel offsets layers

#### 4.4.1.3 Input Files

The *inputs* subgroup ("/science/LSAR/GOFF/metadata/processingInformation/inputs") includes all the input files and granules used to generate the product i.e., L1\_RSLC reference and secondary input granules, a description of the DEM used for processing, configuration files, and orbit files.

#### 4.4.2 Other Radar Metadata

Section 5.5 includes the orbit ephemeris used for generating the L2\_GOFF under a subgroup named "/science/LSAR/GOFF/metadata metadata/orbit".

#### 4.4.2.1 Orbit

The orbit ephemeris used for generating the L2\_GOFF product can be found under a subgroup named "orbit". This group includes time-tagged antenna phase center position and velocity vectors in Earth Centered Earth Fixed (ECEF) cartesian coordinates. In nominal operations, this would be the MOE state vectors that were used by the L2 processor.

#### 4.4.3 Radar Grid

Section 5.6 contains information describing the radar geometry of the sensor during data taking in the group "/science/LSAR/GOFF/metadata/radarGrid/". This information is given in the form of data cubes, referred to as *radar grid cubes*, that are organized over a three-dimensional geographic grid. The representation as data cubes, rather than two-dimensional rasters, is used to reduce the amount of space required to store radar geometry values within NISAR L2 products. This is possible because each radar grid cube contains slowly varying values in space that can be described by a low-resolution three-dimensional grid with sufficient accuracy.

These values, however, are usually required at the terrain height, often characterized by a fastvarying surface representing the local topography. A higher-resolution DEM can then be used to interpolate radar grid cubes and generate high-resolution maps of the corresponding radar geometry variable.

Radar grid cubes (for geocoded products) are provided in the same coordinate system as the product imagery with similar extents (bounding box) but coarser pixel spacing. The threedimensional geographic grid is defined by the HDF5 datasets "xCoordinates" (defining the east component), "yCoordinates" (north component), and "heightAboveEllipsoid" (height above the WGS84 ellipsoid), common to all radar grid cubes, and following the CF-1.8 convention.

Radar grid cubes provide the following list of radar geometry information in the associated HDF5 datasets:

- 1. The zero-Doppler radar grid is defined through the datasets "slantRange" and "zeroDopplerAzimuthTime", which contain respectively the range position in meters and the zero-Dopper azimuth time in seconds for each point of the geographical grid.
- The line-of-sight (LOS) unit vector, i.e., the vector from the target to the sensor, is defined by the datasets "losUnitVectorX" and "losUnitVectorY" which contain respectively the east and north components of the LOS unit vector in the east-north-up (ENU) coordinate system for each point of the geographic grid. Note that the third component of the LOS unit vector is not provided in the product as it can be simply derived from the other two components as:

 $losUnitVectorZ = \sqrt{1 - losUnitVectorX^2 - losUnitVectorY^2}$ 

- 2. The along-track unit vector represents the projection of the along-track vector at the ground height. It is defined by the datasets "alongTrackUnitVectorX" and "alongTrackUnitVectorY" containing respectively the east and north components of the along-track unit vector in UTM coordinates.
- 3. The incidence angle, i.e., the angle between the LOS vector and the normal to the ellipsoid at the target height, is given by the dataset "incidenceAngle.
- 4. The elevation angle, defined as the angle between the LOS vector and the normal to the ellipsoid at the sensor, is provided as "elevationAngle".
- 5. The ground track velocity which contains the absolute value of the platform velocity scaled at the target height is given as "groundTrackVelocity".

## **5 PRODUCT SPECIFICATION**

### 5.1 Dimensions and Shapes

To simplify the description of the layout of data within the HDF5 file, we will use a table of dimensions and shapes to represent the relationship between similarly sized datasets. The entries in this table do not present actual datasets in the HDF5. This table is meant to be a guide to interpreting the shapes of the datasets in subsequent subsections.

Name	Shape	Description
scalar	scalar	None
numberOfDatatakes	scalar	number of datatakes in product
numberOfObservations	scalar	number of observations in product
numberOfFrequencies	scalar	Number of L-SAR frequencies in product
numberOfFrequencyAPolarizations	scalar	Number of polarization layers associated with L-SAR frequency A
frequencyAWidth	scalar	Number of pixels in all L-SAR frequency A imagery datasets
frequencyALength	scalar	Number of lines in all L-SAR frequency A imagery datasets
complexDataFrequencyAShape	(frequencyALength, frequencyAWidth)	Shape associated with L-SAR frequency A imagery datasets
realDataFrequencyAShape	(frequencyALength, frequencyAWidth)	Shape associated with L-SAR frequency A imagery interferometric dataset
offsetDataShape	(offsetLength, offsetWidth)	Shape associated with Pixel Offset layers
offsetWidth	scalar	Number of pixels in Pixel Offset layers
offsetLength	scalar	Number of lines in all L-SAR frequency A imagery datasets
radarGridShape	(radarCubeLength, radarCubeWidth)	Shape associated with 2D rasters on same grid as metadata cubes
radarCubeShape	(radarCubeHeight, radarCubeLength, radarCubeWidth)	Shape associated with metadata cubes

Table 5-1 Table of dimensions and shapes in L2\_GOFF product

twoLayersCubeShape	(radarCubeWidth, radarCubeLength, twoLayersCubeHeight)	Shape associated with baseline metadata cubes
radarCubeHeight	scalar	Height dimension of the metadata cube
radarCubeLength	scalar	Length dimension of the metadata cube
radarCubeWidth	scalar	Width dimension of the metadata cube
twoLayersCubeHeight	scalar	Height dimension of the baseline metadata cube
dopplerCentroidLength	scalar	Length dimension of Doppler centroid grid
dopplerCentroidWidth	scalar	Length dimension of Doppler centroid grid
dopplerCentroidShape	(dopplerCentroidLength, dopplerCentroidWidth)	Shape of the Doppler centroid grid
calibrationLength	scalar	Length of calibration LUTs
calibrationWidth	scalar	Width of calibration LUTs
calibrationScaleShape	(calibrationLength, calibrationWidth)	Shape of calibration LUTs
antennaPatternComplexShape	(calibrationLength, calibrationWidth)	Shape of antenna pattern datasets
orbitListLength	scalar	description="Number of orbit state vectors
orbitShape	(orbitListLength, 3)	Shape of orbit state vector triplets dataset
attitudeListLength	scalar	Number of attitude state vectors
attitudeQuaternionShape	(attitudeListLength, 4)	Shape of attitude quaternion dataset
attitudeShape	(attitudeListLength, 3)	Shape of attitude Euler angle triplets dataset
chirpWeightingFrequencyLength	scalar	Shape associated with 1D filter representations in frequency domain
numberOfInputL1Files	scalar	Number of input L1 granules
numberOfInputOrbitFiles	scalar	Number of input orbit files
numberOfInputConfigFiles	scalar	Number of input configuration files

## 5.2 Product Identification

#### Table 5-2 NISAR HDF5 variables used for product identification

Product Identification Variables		
/science/LSAR/identification/absoluteOrbitNumber		
Type: UInt32	Shape: scalar	
Description: Absolute orbit number		
units	unitless	
/science/LSAR/identification/trackNumber	r	
Type: UByte	Shape: scalar	
Description: Track number		
units	unitless	
/science/LSAR/identification/frameNumbe	r	
Type: UInt16	Shape: scalar	
Description: Frame number		
units	unitless	
/science/LSAR/identification/missionId		
Type: string	Shape: scalar	
Description: Mission identifier		
/science/LSAR/identification/processingC	enter	
Type: string	Shape: scalar	
Description: Data processing center		
/science/LSAR/identification/productType		
Type: string	Shape: scalar	
Description: Product type		
/science/LSAR/identification/granuleld		
Type: string	Shape: scalar	
Description: Unique granule identification name		
/science/LSAR/identification/productVers	ion	
Type: string	Shape: scalar	
Description: Product version which represents the structure of the product and the science content governed by the		
algorithm, input data, and processing parameters		
/science/LSAR/identification/productSpec	ificationVersion	
Type: string	Shape: scalar	
Description: Product specification version which represents the schema of this product		
/science/LSAR/identification/lookDirection	1	
Type: string	Shape: scalar	
Description: Look direction can be left or right		
/science/LSAR/identification/orbitPassDir	ection	

Type: string	Shape: scalar	
Description: Orbit direction can be ascendi	ng or descending	
/science/LSAR/identification/referenceZe	roDopplerStartTime	
Type: string	Shape: scalar	
Description: Azimuth start time of reference	e RSLC product	
/science/LSAR/identification/secondaryZ	eroDopplerStartTime	
Type: string	Shape: scalar	
Description: Azimuth start time of secondar	ry RSLC product	
/science/LSAR/identification/referenceZe	roDopplerEndTime	
Type: string	Shape: scalar	
Description: Azimuth stop time of reference	e RSLC product	
/science/LSAR/identification/secondaryZ	eroDopplerEndTime	
Type: string	Shape: scalar	
Description: Azimuth stop time of secondar	ry RSLC product	
/science/LSAR/identification/plannedData	atakeld	
Type: string	Shape: (numberOfDatatakes)	
Description: List of planned datatakes inclu	ded in the product	
/science/LSAR/identification/plannedObs	ervationId	
Type: string	Shape: (numberOfObservations)	
Description: List of planned observations in	cluded in the product	
/acianaa/LSAB/idantification/iol/reantObs	nonvetion.	
Type: string	Shane: scalar	
Description: Boolean indicating if observati	on is nominal or urgent	
/science/LSAR/identification/listOfFreque	encies	
Type: string	Shape: (numberOfFrequencies)	
<b>Description:</b> List of frequency layers available	ble in the product	
/science/LSAR/identification/diagnosticM	lodeFlag	
Type: UByte	Shape: scalar	
Description: Indicates if the radar operation DBFed science (0): 0, 1, or 2	n mode is a diagnostic mode (1-2) or	
unito	unitlaga	
Units	l unitiess	
Type: string	Shane: scalar	
Description: Product level 104: Upprocess	ed instrument data: LOB: Reformatted unprocessed instrument data: L1:	
Processed instrument data in radar coordinates system; and L2: Processed instrument data in geocoded coordinates		
system		
/science/LSAR/identification/isGeocoded		
Type: string	Shape: scalar	
Description: Flag to indicate if the product of	data is in the radar geometry ("False") or in the map geometry ("True")	
/science/LSAR/identification/boundingPolygon		
Type: string	Shape: scalar	

Description: OGR compatible WKT representation of bounding polygon of the image		
/science/LSAR/identification/processingDateTime		
Type: string	Shape: scalar	
Description: Processing UTC date and time	in the format YYYY-MM-DDTHH:MM:SS	
/science/LSAR/identification/radarBand		
Type: string	Shape: scalar	
Description: Acquired frequency band		
/science/LSAR/identification/instrumentN	ame	
Type: string	Shape: scalar	
Description: Name of the instrument used to collect the remote sensing data provided in this product		
/science/LSAR/identification/processingT	уре	
Type: string	Shape: scalar	
Description: NOMINAL (or) URGENT (or) CUSTOM (or) UNDEFINED		
/science/LSAR/identification/isDithered		
Type: string	Shape: scalar	
Description: "True" if the pulse timing was varied (dithered) during acquisition, "False" otherwise.		
/science/LSAR/identification/isMixedMode		
Type: string	Shape: scalar	
Description: "True" if this product is a composite of data collected in multiple radar modes, "False" otherwise.		

## 5.3 Radar Imagery

#### Table 5-3 NISAR HDF5 variables related to SAR imagery

Product Imagery Variables		
/science/LSAR/GOFF/grids/frequencyA/listO	fPolarizations	
Type: string	Shape: (numberOfFrequencyAPolarizations)	
Description: List of processed polarization layers with frequencyA		
/science/LSAR/GOFF/grids/frequencyA/cent	erFrequency	
Type: Float64	Shape: scalar	
Description: Center frequency of the processed image in Hz		
units	Hz	
/science/LSAR/GOFF/grids/frequencyA/pixe	Offsets/HH/layer1/projection	
Type: Int32	Shape: scalar	
Description: Product map grid projection: EPS	G code, with additional projection information as HDF5 Attributes	
ellipsoid	Projection ellipsoid	
epsg_code	Projection EPSG code	
false_easting	The value added to all abscissa values in the rectangular coordinates for a map projection.	
false_northing	The value added to all ordinate values in the rectangular coordinates for a map projection.	
grid_mapping_name	Grid mapping variable name	
inverse_flattening	Inverse flattening of the ellipsoidal figure	
latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map projection.	
longitude_of_projection_origin	The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum.	
semi_major_axis	Semi-major axis	
spatial_ref	Spatial reference	
utm_zone_number	UTM zone number	
/science/LSAR/GOFF/grids/frequencyA/pixe	IOffsets/HH/layer1/yCoordinateSpacing	
Type: Float64	Shape: scalar	
Description: Nominal spacing in meters betwe	en consecutive lines	
long_name	Y coordinates spacing	
units	meters	
/science/LSAR/GOFF/grids/frequencyA/pixe	Offsets/HH/layer1/xCoordinateSpacing	
Type: Float64	Shape: scalar	
Description: Nominal spacing in meters between consecutive pixels		
long_name	X coordinates spacing	
units	meters	
/science/LSAR/GOFF/grids/frequencyA/pixe	Offsets/VV/layer1/projection	
Type: Int32	Shape: scalar	
Description: Product map grid projection: EPS	G code, with additional projection information as HDF5 Attributes	
ellipsoid	Projection ellipsoid	
epsg_code	Projection EPSG code	

false_easting	The value added to all abscissa values in the rectangular coordinates for a map projection.
false_northing	The value added to all ordinate values in the rectangular coordinates
grid mapping name	Grid mapping variable name
inverse flattening	Inverse flattening of the ellipsoidal figure
latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map projection.
longitude_of_projection_origin	The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum.
semi major axis	Semi-major axis
spatial ref	Spatial reference
utm_zone_number	UTM zone number
/science/LSAR/GOFF/grids/frequencyA/	pixelOffsets/VV/layer1/yCoordinateSpacing
Type: Float64	Shape: scalar
Description: Nominal spacing in meters b	etween consecutive lines
long_name	Y coordinates spacing
units	meters
/science/LSAR/GOFF/grids/frequencyA/	pixelOffsets/VV/layer1/xCoordinateSpacing
Type: Float64	Shape: scalar
Description: Nominal spacing in meters b	etween consecutive pixels
long_name	X coordinates spacing
units	meters
/science/LSAR/GOFF/grids/frequencyA	pixelOffsets/HH/layer2/projection
Type: Int32	Shape: scalar
Description: Product map grid projection:	EPSG code, with additional projection information as HDF5 Attributes
ellipsoid	Projection ellipsoid
epsq code	Projection EPSG code
false easting	The value added to all abscissa values in the rectangular coordinates
	for a map projection.
false_northing	The value added to all ordinate values in the rectangular coordinates for a map projection.
grid mapping name	Grid mapping variable name
inverse flattening	Inverse flattening of the ellipsoidal figure
latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map projection.
longitude_of_projection_origin	The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum.
semi_major_axis	Semi-major axis
spatial_ref	Spatial reference
utm_zone_number	UTM zone number
/science/LSAR/GOFF/grids/frequencyA/	pixelOffsets/HH/layer2/yCoordinateSpacing
Type: Float64	Shape: scalar
Description: Nominal spacing in meters b	etween consecutive lines
long name	Y coordinates spacing
units	meters
/science/LSAR/GOFF/grids/frequencvA	pixelOffsets/HH/layer2/xCoordinateSpacing
Type: Float64	Shape: scalar
Description: Nominal spacing in meters b	etween consecutive pixels

long_name	X coordinates spacing	
units	meters	
/science/LSAR/GOFF/grids/frequencyA/pixe	elOffsets/VV/layer2/projection	
Type: Int32	Shape: scalar	
Description: Product map grid projection: EPS	G code, with additional projection information as HDF5 Attributes	
ellipsoid	Projection ellipsoid	
epsa code	Projection EPSG code	
false easting	The value added to all abscissa values in the rectangular coordinates	
5	for a map projection.	
false northing	The value added to all ordinate values in the rectangular coordinates	
	for a map projection.	
grid mapping name	Grid mapping variable name	
inverse flattening	Inverse flattening of the ellipsoidal figure	
latitude of projection origin	The latitude chosen as the origin of rectangular coordinates for a map	
	projection.	
longitude of projection origin	The longitude, with respect to Greenwich, of the prime meridian	
	associated with the geodetic datum.	
semi major axis	Semi-major axis	
spatial ref	Spatial reference	
utm zone number	UTM zone number	
/science/LSAR/GOFF/grids/frequencyA/pixe	elOffsets/VV/laver2/vCoordinateSpacing	
Type: Float64	Shape: scalar	
Description: Nominal spacing in meters between	een consecutive lines	
long name	Y coordinates spacing	
units	meters	
/science/LSAR/GOFF/grids/frequencvA/pixe	elOffsets/VV/laver2/xCoordinateSpacing	
Type: Float64	Shape: scalar	
<b>Description:</b> Nominal spacing in meters between	een consecutive pixels	
long name	X coordinates spacing	
units	meters	
/science/LSAR/GOFF/grids/frequencyA/pixe	elOffsets/HH/laver3/projection	
Type: Int32	Shape: scalar	
<b>Description:</b> Product map grid projection: EPS	SG code, with additional projection information as HDF5 Attributes	
ellipsoid	Projection ellipsoid	
ensa code	Projection EPSG code	
false easting	The value added to all abscissa values in the rectangular coordinates	
	for a map projection.	
false northing	The value added to all ordinate values in the rectangular coordinates	
	for a map projection.	
grid mapping name	Grid mapping variable name	
inverse flattening	Inverse flattening of the ellipsoidal figure	
latitude of projection origin	The latitude chosen as the origin of rectangular coordinates for a map	
	projection.	
longitude of projection origin	The longitude, with respect to Greenwich, of the prime meridian	
	associated with the geodetic datum.	
semi maior axis	Semi-maior axis	
spatial ref	Spatial reference	
utm zone number	UTM zone number	
/science/I_SAR/GOFF/grids/frequencyA/pixelOffsets/HH/laver3/vCoordinateSpacing		
Type: Float64	Shape: scalar	

Description: Nominal spacing in meters between consecutive lines		
		Verendiestes species
	iong_name	r coordinates spacing
Iscience	UNITS	There is a second secon
Type: Elect64		
Descript	ion: Nominal spacing in meters betwee	n consecutive nixels
Descript	ion. Norminal spacing in meters betwee	
	long_name	X coordinates spacing
	units	meters
/science/	/LSAR/GOFF/grids/frequencyA/pixel0	Offsets/VV/layer3/projection
Type: Int	32	Shape: scalar
Descript	ion: Product map grid projection: EPSG	Code, with additional projection information as HDF5 Attributes
	ellipsoid	Projection ellipsoid
	epsg_code	Projection EPSG code
	false_easting	I he value added to all abscissa values in the rectangular coordinates
	falas as this s	for a map projection.
	raise_nortning	for a man projection
	arid monning nome	for a map projection.
	gliu_mapping_name	Gild mapping variable name
	Inverse_nation_origin	The latitude abasen as the origin of restangular searchington for a man
		projection.
	longitude of projection origin	The longitude, with respect to Greenwich, of the prime meridian
	5 5	associated with the geodetic datum.
	semi_major_axis	Semi-major axis
	spatial_ref	Spatial reference
	utm_zone_number	UTM zone number
/science/	/LSAR/GOFF/grids/frequencyA/pixel0	Offsets/VV/layer3/yCoordinateSpacing
Type: Flo	oat64	Shape: scalar
Descript	ion: Nominal spacing in meters betwee	n consecutive lines
	long_name	Y coordinates spacing
	units	meters
/science/	/LSAR/GOFF/grids/frequencyA/pixel	Dffsets/VV/layer3/xCoordinateSpacing
Type: Flo	oat64	Shape: scalar
Descript	ion: Nominal spacing in meters betwee	n consecutive pixels
	long_name	X coordinates spacing
	units	meters
/science/	/LSAR/GOFF/grids/frequencyA/pixel0	Dffsets/HH/layer1/xCoordinates
Type: Flo	oat64	Shape: (offsetWidth)
Descript	ion: CF compliant dimension associated	d with the X coordinates
	long_name	X coordinate of projection
	standard_name	projection_x_coordinate
	units	meters
/science	/LSAR/GOFF/grids/frequencyA/pixel0	Dffsets/HH/layer1/yCoordinates
Type: Flo	pat64	Shape: (offsetLength)
Descript	ion: CF compliant dimension associated	d with the Y coordinates
	long name	Y coordinate of projection
	standard_name	projection_y_coordinate

units	meters	
/science/LSAR/GOFF/grids/frequencyA/pixelOffsets/VV/layer1/xCoordinates		
Type: Float64 Shape: (offsetWidth)		
Description: CF compliant din	ension associated with the X coordinates	
<b>f</b> f		
long_name	X coordinate of projection	
standard_name	projection_x_coordinate	
units	meters	
/science/LSAR/GOFF/grids/fi	quencyA/pixelOffsets/VV/layer1/yCoordinates	
Type: Float64	Shape: (offsetLength)	
Description: CF compliant din	ension associated with the Y coordinates	
long name	Y coordinate of projection	
standard name		
	projection_y_coordinate	
/science/I SAR/GOFE/grids/fu	guencyA/nixelOffsets/HH/laver2/xCoordinates	
Type: Float64	Shane: (offsetWidth)	
Description: CE compliant din	ansion associated with the X coordinates	
	STORE ASSOCIATED WITH THE A COOLUINATES	
long_name	X coordinate of projection	
standard_name	projection_x_coordinate	
units	meters	
/science/LSAR/GOFF/grids/fi	quencyA/pixelOffsets/HH/layer2/yCoordinates	
Type: Float64	Shape: (offsetLength)	
Description: CF compliant din	ension associated with the Y coordinates	
• •		
long_name	Y coordinate of projection	
standard_name	projection_y_coordinate	
units	meters	
/science/LSAR/GOFF/grids/fi	quencyA/pixelOffsets/VV/layer2/xCoordinates	
Type: Float64	Shape: (offsetWidth)	
Description: CF compliant dimension associated with the X coordinates		
long name	X coordinate of projection	
standard name	projection x coordinate	
	meters	
/science/LSAR/GOFF/grids/fi	quencvA/pixelOffsets/VV/laver2/vCoordinates	
Type: Float64	Shape: (offsetl ength)	
Description: CF compliant din	ension associated with the Y coordinates	
long_name	Y coordinate of projection	
standard_name	projection_y_coordinate	
units	meters	
/science/LSAR/GOFF/grids/fi	quencyA/pixelOffsets/HH/layer3/xCoordinates	
Type: Float64	Shape: (offsetWidth)	
Description: CF compliant din	ension associated with the X coordinates	
long_name	X coordinate of projection	
standard_name	projection_x_coordinate	
units	meters	
/science/LSAR/GOFF/grids/fi	quencyA/pixelOffsets/HH/layer3/yCoordinates	
Type: Float64	Shape: (offsetLength)	

Description: CF compliant	nt dimension associated v	with the Y coordinates
		V according to of projection
standard nam	~ · · · ·	
unite		meters
/science/LSAR/GOFF/gr	ids/frequencyA/nixelOff	fsets/W/laver3/xCoordinates
Type: Float64	S	Shape: (offsetWidth)
Description: CF complia	nt dimension associated v	with the X coordinates
long_name	)	X coordinate of projection
standard_nam	e p	projection_x_coordinate
units	r	meters
/science/LSAR/GOFF/gr	ids/frequencyA/pixelOff	fsets/VV/layer3/yCoordinates
Type: Float64	S	hape: (offsetLength)
Description: CF compliant dimension associated with the Y coordinates		
long_name	N	Y coordinate of projection
standard_nam	e	projection_y_coordinate
units	r	meters
/science/LSAR/GOFF/gr	ids/frequencyA/pixelOff	fsets/HH/layer1/alongTrackOffset
Type: Float32	S	hape: (offsetLength, offsetWidth)
Description: Raw (uncul	ed, unfiltered) along-track	k pixel offsets
_FillValue	r	nan
grid_mapping	ł	projection
units	r	meters
/science/LSAR/GOFF/gr	ids/frequencyA/pixelOff	fsets/HH/layer1/slantRangeOffset
Type: Float32	S	hape: (offsetLength, offsetWidth)
Description: Raw (uncul	ed, unfiltered) slant range	e pixel offsets
_FillValue	r	nan
grid_mapping	1	projection
units	r	meters
/science/LSAR/GOFF/gr	ids/frequencyA/pixelOff	fsets/HH/layer1/correlationSurfacePeak
Type: Float32	S	hape: (offsetLength, offsetWidth)
Description: Normalized	correlation surface peak	
_FillValue	r	nan
grid_mapping	ł	projection
units	ι	unitless
/science/LSAR/GOFF/gr	ids/frequencyA/pixelOff	fsets/HH/layer1/crossOffsetVariance
Type: Float32	S	hape: (offsetLength, offsetWidth)
Description: Off-diagona	I term of the pixel offsets	covariance matrix
FillValue	r	nan
grid_mapping	I I	projection
units	l	unitless
/science/LSAR/GOFF/gr	ids/frequencyA/pixelOff	fsets/HH/layer1/slantRangeVariance
Type: Float32	S	hape: (offsetLength, offsetWidth)
Description: Slant range	pixel offsets variance	
units	L	unitless
/science/LSAR/GOFE/gr	ids/frequencyA/pixelOff	fsets/HH/laver1/alongTrackOffsetVariance

Type: Flo	pat32	Shape: (offsetLength, offsetWidth)	
Descript	ion: Along-track pixel offsets variance	· · · · · · · · · · · · · · · · · · ·	
-	- ·		
	_FillValue	nan	
	grid_mapping	projection	
	units	unitless	
/science	/LSAR/GOFF/grids/frequencyA/pixel	Offsets/HH/layer1/snr	
Type: Fl	oat32	Shape: (offsetLength, offsetWidth)	
Descript	ion: Pixel offsets signal-to-noise ratio		
	_FillValue	nan	
	grid_mapping	projection	
	units	unitless	
/science	/science/LSAR/GOFF/grids/frequencyA/pixelOffsets/HH/layer2/alongTrackOffset		
Type: Flo	pat32	Shape: (offsetLength, offsetWidth)	
Descript	ion: Raw (unculled, unfiltered) along-tra	ack pixel offsets	
	_FillValue	nan	
		projection	
	units	meters	
/science	/LSAR/GOFF/grids/frequencyA/pixel	Offsets/HH/layer2/slantRangeOffset	
Type: Flo	oat32	Shape: (offsetLength, offsetWidth)	
Descript	ion: Raw (unculled, unfiltered) slant rar	nge pixel offsets	
	_FillValue	nan	
-	grid_mapping	projection	
	units	meters	
/science	/LSAR/GOFF/grids/frequencyA/pixel	Offsets/HH/layer2/correlationSurfacePeak	
Type: Flo	pat32	Shape: (offsetLength, offsetWidth)	
Descript	ion: Normalized correlation surface pea	ak	
	_FillValue	nan	
	grid_mapping	projection	
	units	unitless	
/science	/LSAR/GOFF/grids/frequencyA/pixel	Offsets/HH/layer2/crossOffsetVariance	
Type: Flo	pat32	Shape: (offsetLength, offsetWidth)	
Descript	ion: Off-diagonal term of the pixel offse	ts covariance matrix	
	_FillValue	nan	
	grid_mapping	projection	
	units	unitless	
/science	LSAR/GOFF/grids/frequencyA/pixel	Offsets/HH/layer2/slantRangeOffsetVariance	
Type: Flo	pat32	Shape: (offsetLength, offsetWidth)	
Descript	ion: Slant range pixel offsets variance		
	_FillValue	nan	
	grid mapping	projection	
	units	unitless	
/science	/LSAR/GOFF/grids/frequencyA/pixel	Offsets/HH/layer2/alongTrackOffsetVariance	
Type: Fl	pat32	Shape: (offsetLength, offsetWidth)	
Description: Along-track pixel offsets variance			
	FillValue	nan	
L			

grid mapping	projection		
units	unitless		
/science/LSAR/GOFF/grids/frequencyA/pixel	Offsets/HH/laver2/snr		
Type: Float32	Shape: (offsetl ength, offsetWidth)		
<b>Description:</b> Pixel offsets signal-to-noise ratio			
FillValue	nan		
arid mapping	projection		
units	unitless		
/science/LSAR/GOFF/grids/frequencyA/pixel	Offsets/HH/laver3/alongTrackOffset		
Type: Float32	Shape: (offsetLength, offsetWidth)		
Description: Raw (unculled, unfiltered) along-tra	ack pixel offsets		
_FillValue	nan		
grid_mapping	projection		
units	meters		
/science/LSAR/GOFF/grids/frequencyA/pixel	Offsets/HH/layer3/slantRangeOffset		
Type: Float32	Shape: (offsetLength, offsetWidth)		
Description: Raw (unculled, unfiltered) slant rar	nge pixel offsets		
_FillValue	nan		
grid_mapping	projection		
units	meters		
/science/LSAR/GOFF/grids/frequencyA/pixel	Offsets/HH/layer3/correlationSurfacePeak		
Type: Float32	Shape: (offsetLength, offsetWidth)		
Description: Normalized correlation surface pea	ak		
	1		
FillValue	nan		
grid_mapping	projection		
units	unitless		
/science/LSAR/GOFF/grids/frequencyA/pixel	Offsets/HH/layer3/crossOffsetVariance		
Type: Float32	Shape: (offsetLength, offsetWidth)		
<b>Description:</b> Off-diagonal term of the pixel offse	ts covariance matrix		
EUN / a luca			
	nan		
grid_mapping			
	Unitiess		
/science/LSAR/GUFF/grids/frequencyA/pixel	Diffsets/HH/layer3/slantRangeOffsetVariance		
Type: Floatsz	Shape: (onsetLength, onsetwidth)		
Description: Siant range pixel onsets variance			
FillValue	nan		
grid_mapping			
/science/LSAR/GOEE/grids/frequencyA/nivel/	Offsets/HH/laver3/alongTrackOffsetVariance		
Type: Float32	Shape: (offsetl ength_offsetWidth)		
<b>Description:</b> Along-track pixel offsets variance	onape. (onseteenigen, onsetematin)		
Besonption. Along-track pixel onsets valiance			
FillValue	nan		
grid mapping	projection		
units	unitless		
/science/LSAR/GOFF/arids/frequencyA/nixel	/science/l SAR/GOFF/grids/frequencyA/nixelOffsets/HH/laver3/spr		
Type: Float32	Shape: (offsetLength, offsetWidth)		

Description: Pixel offsets signal-to-noise ratio	
FillValua	nan
unite	
/science/LSAR/GOFE/grids/frequencyA/nivel/	) Tifsets/WV/laver1/alongTrackOffset
Type: Float32	Shane: (offset) ength_offsetWidth)
<b>Description:</b> Raw (unculled unfiltered) along-tra	ack nivel offsats
_FillValue	nan
grid_mapping	projection
units	meters
/science/LSAR/GOFF/grids/frequencyA/pixel	Offsets/VV/layer1/slantRangeOffset
Type: Float32	Shape: (offsetLength, offsetWidth)
Description: Raw (unculled, unfiltered) slant rar	nge pixel offsets
_FillValue	nan
grid_mapping	projection
units	meters
/science/LSAR/GOFF/grids/frequencyA/pixel	Offsets/VV/layer1/correlationSurfacePeak
Type: Float32	Shape: (offsetLength, offsetWidth)
Description: Normalized correlation surface pea	ak
	nan
grid_mapping	
/science/LSAR/GOFF/grids/frequencyA/pixel	Offsets/vv/layer1/crossOffsetvariance
Type: Float32	Snape: (offsetLength, offsetWidth)
Description: On-diagonal term of the pixel onse	is covariance mainx
_FillValue	nan
grid_mapping	projection
units	unitless
/science/LSAR/GOFF/grids/frequencyA/pixel	Offsets/VV/layer1/slantRangeOffsetVariance
Type: Float32	Shape: (offsetLength, offsetWidth)
Description: Slant range pixel offsets variance	
_FillValue	nan
grid_mapping	projection
units	unitless
/science/LSAR/GOFF/grids/frequencyA/pixel	Offsets/VV/layer1/alongTrackOffsetVariance
Type: Float32	Shape: (offsetLength, offsetWidth)
Description: Along-track pixel offsets variance	
_FillValue	nan
grid_mapping	projection
units	unitless
/science/LSAR/GOFF/grids/frequencyA/pixel	Offsets/VV/layer1/snr
Type: Float32	Shape: (offsetLength, offsetWidth)
Description: Pixel offsets signal to noise ratio	
FillValue	nan
grid mapping	projection

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/science/LSAR/GOFF/grids/frequencyA/pixel	Offsets/VV/layer2/along1rackOffset	
Type: Float32	Shape: (offsetLength, offsetWidth)	
Description: Raw (unculled, unfiltered) along-tra	ack pixel offsets	
FillValue	nan	
grid mapping	projection	
units	meters	
/science/LSAR/GOFF/grids/frequencyA/pixel	Dffsets/VV/laver2/slantRangeOffset	
Type: Float32	Shape: (offsetLength, offsetWidth)	
Description: Raw (unculled, unfiltered) slant range pixel offsets		
_FillValue	nan	
grid_mapping	projection	
units	meters	
/science/LSAR/GOFF/grids/frequencyA/pixel	Dffsets/VV/layer2/correlationSurfacePeak	
Type: Float32	Shape: (offsetLength, offsetWidth)	
Description: Normalized correlation surface pea	ik ,	
FillValue	nan	
grid mapping	projection	
units	unitless	
/science/LSAR/GOFF/grids/frequencvA/pixel	Dffsets/VV/laver2/crossOffsetVariance	
Type: Float32	Shape: (offsetLength, offsetWidth)	
<b>Description:</b> Off-diagonal term of the pixel offse	ts covariance matrix	
_FillValue	nan	
grid_mapping	projection	
units	unitless	
/science/LSAR/GOFF/grids/frequencyA/pixel	Offsets/VV/layer2/slantRangeOffsetVariance	
Type: Float32	Shape: (offsetLength, offsetWidth)	
<b>Description:</b> Slant range pixel offsets variance		
_FillValue	nan	
grid_mapping	projection	
units	unitless	
/science/LSAR/GOFF/grids/frequencyA/pixel	Dffsets/VV/layer2/alongTrackOffsetVariance	
Type: Float32	Shape: (offsetLength, offsetWidth)	
Description: Along-track pixel offsets variance		
_FillValue	nan	
grid mapping	projection	
units	unitless	
/science/LSAR/GOFF/grids/frequencyA/pixel	Dffsets/VV/laver2/snr	
Type: Float32	Shape: (offsetLength, offsetWidth)	
Description: Pixel offsets signal-to-noise ratio		
_FillValue	nan	
grid_mapping	projection	
units	unitless	
/science/LSAR/GOFF/grids/freguencyA/pixelOffsets/VV/laver3/alongTrackOffset		
Type: Float32	Shape: (offsetLength, offsetWidth)	

Descript	ion: Raw (unculled, unfiltered) along-tra	ick pixel offsets
	_FillValue	nan
	grid_mapping	projection
	units	meters
/science/	LSAR/GOFF/grids/frequencyA/pixelC	Dffsets/VV/layer3/slantRangeOffset
Type: Flo	pat32	Shape: (offsetLength, offsetWidth)
Descript	ion: Raw (unculled, unfiltered) slant ran	ge pixel offsets
	_FillValue	nan
	grid_mapping	projection
	units	meters
/science/	LSAR/GOFF/grids/frequencyA/pixelC	Offsets/VV/layer3/correlationSurfacePeak
Type: Flo	pat32	Shape: (offsetLength, offsetWidth)
Description: Normalized correlation surface peak		
	_FillValue	nan
	grid_mapping	projection
	units	unitless
/science/	LSAR/GOFF/grids/frequencyA/pixelC	Offsets/VV/layer3/crossOffsetVariance
Type: Flo	pat32	Shape: (offsetLength, offsetWidth)
Descript	ion: Off-diagonal term of the pixel offset	ts covariance matrix
	_FillValue	nan
	grid_mapping	projection
	units	unitless
/science/	LSAR/GOFF/grids/frequencyA/pixelC	Offsets/VV/layer3/slantRangeOffsetVariance
Type: Flo	pat32	Shape: (offsetLength, offsetWidth)
Descript	ion: Slant range pixel offsets variance	
	_FillValue	nan
	grid_mapping	projection
	units	unitless
/science/LSAR/GOFF/grids/frequencyA/pixelOffsets/VV/laver3/alongTrackOffsetVariance		
Type: Flo	pat32	Shape: (offsetLength, offsetWidth)
Descript	ion: Along-track pixel offsets variance	
	_FillValue	nan
	grid_mapping	projection
	units	unitless
/science/	LSAR/GOFF/grids/frequencyA/pixelC	) Dffsets/VV/layer3/snr
Type: Flo	pat32	Shape: (offsetLength, offsetWidth)
Descript	ion: Pixel offsets signal-to-noise ratio	
	FillValue	nan
	grid mapping	projection
	units	unitless

## 5.4 Processing Information

#### Table 5-4 NISAR HDF5 variables related to processing parameters

Processing-related variables		
/science/LSAR/GOFF/metadata/processin	gInformation/parameters/runConfigurationContents	
Type: string	Shape: scalar	
Description: Contents of the run configuration file with parameters used for processing		
/science/LSAR/GOFF/metadata/processin	gInformation/parameters/reference/referenceTerrainHeight	
Type: Float32	Shape: (dopplerCentroidLength, dopplerCentroidWidth)	
Description: Reference Terrain Height as a	function of map coordinates for reference RSLC	
units	meters	
/science/LSAR/GOFF/metadata/processir	gInformation/parameters/reference/rfiCorrectionApplied	
Type: string Shape: scalar		
Description: Flag to indicate if RFI correction	n has been applied to reference RSLC	
/science/LSAR/GOFF/metadata/processin	gInformation/parameters/reference/isMixedMode	
Type: string	Shape: scalar	
<b>Description:</b> "True" if reference RSLC is a c	composite of data collected in multiple radar modes, "False" otherwise	
/science/LSAR/GOFF/metadata/processin	gInformation/parameters/reference/frequencyA/slantRangeSpacing	
Type: Float64	Shape: scalar	
Description: Slant range spacing of referen	ce RSLC	
units	meters	
/science/LSAR/GOFF/metadata/processin	gInformation/parameters/reference/frequencyA/zeroDopplerTimeSpacing	
Type: Float64	Shape: scalar	
Description: Time interval in the along-track layers	direction for reference RSLC raster	
units	seconds	
/science/LSAR/GOFF/metadata/processin	gInformation/parameters/reference/frequencyA/rangeBandwidth	
Type: Float64	Shape: scalar	
Description: Processed slant range bandwi	dth for reference RSLC	
units	Hz	
/science/LSAR/GOFF/metadata/processin	gInformation/parameters/reference/frequencyA/azimuthBandwidth	
Type: Float64	Shape: scalar	
Description: Processed azimuth bandwidth for reference RSLC		
	for reference RSLC	
units	for reference RSLC Hz	
units /science/LSAR/GOFF/metadata/processir	for reference RSLC Hz IgInformation/parameters/reference/frequencyA/dopplerCentroid	
units /science/LSAR/GOFF/metadata/processir Type: Float64	for reference RSLC Hz glnformation/parameters/reference/frequencyA/dopplerCentroid Shape: (dopplerCentroidLength, dopplerCentroidWidth)	
units /science/LSAR/GOFF/metadata/processir Type: Float64 Description: 2D LUT of Doppler Centroid for	for reference RSLC Hz glnformation/parameters/reference/frequencyA/dopplerCentroid Shape: (dopplerCentroidLength, dopplerCentroidWidth) or Frequency A	
units /science/LSAR/GOFF/metadata/processir Type: Float64 Description: 2D LUT of Doppler Centroid fo	for reference RSLC Hz glnformation/parameters/reference/frequencyA/dopplerCentroid Shape: (dopplerCentroidLength, dopplerCentroidWidth) r Frequency A Hz	
units /science/LSAR/GOFF/metadata/processir Type: Float64 Description: 2D LUT of Doppler Centroid fo units /science/LSAR/GOFF/metadata/processir	for reference RSLC Hz glnformation/parameters/reference/frequencyA/dopplerCentroid Shape: (dopplerCentroidLength, dopplerCentroidWidth) or Frequency A Hz glnformation/parameters/secondary/rfiCorrectionApplied	

Description: Flag to indicate if RFI correction	on has been applied to secondary RSLC
/science/LSAR/GOFF/metadata/processir	gInformation/parameters/secondary/isMixedMode
Type: string	Shape: scalar
Description: "True" if secondary RSLC is a	composite of data collected in multiple radar modes, "False" otherwise
/science/LSAR/GOFF/metadata/processir	ngInformation/parameters/secondary/referenceTerrainHeight
Type: Float32	Shape: (dopplerCentroidLength, dopplerCentroidWidth)
<b>Description:</b> Reference Terrain Height as a	function of map coordinates for secondary RSLC
units	meters
/science/LSAR/GOFF/metadata/processin	gInformation/parameters/secondary/frequencyA/dopplerCentroid
Type: Float64	Shape: (dopplerCentroidLength, dopplerCentroidWidth)
Description: 2D LUT of Doppler Centroid for	r Frequency A
units	Hz
/science/LSAR/GOFF/metadata/processir	gInformation/parameters/secondary/frequencyA/slantRangeSpacing
Type: Float64	Shape: scalar
Description: Slant range spacing of second	lary RSLC
units	meters
/science/LSAR/GOFF/metadata/processin	gInformation/parameters/secondary/frequencyA/zeroDopplerTimeSpacing
Type: Float64	Shape: scalar
Description: Time interval in the along-track layers	k direction for secondary RSLC raster
units	seconds
/science/LSAR/GOFF/metadata/processir	gInformation/parameters/secondary/frequencyA/rangeBandwidth
Type: Float64	Shape: scalar
Description: Processed slant range bandwi	dth for secondary RSLC
units	Hz
/science/LSAR/GOFF/metadata/processin	gInformation/parameters/secondary/frequencyA/azimuthBandwidth
Type: Float64	Shape: scalar
Description: Processed azimuth bandwidth	for secondary RSLC
units	Hz
/science/LSAR/GOFF/metadata/processin	gInformation/parameters/common/frequencyA/dopplerCentroid
Type: Float64	Shape: (dopplerCentroidLength, dopplerCentroidWidth)
Description: 2D LUT of Doppler Centroid for	r Frequency A
units	Hz
/science/LSAR/GOFF/metadata/processin	gInformation/parameters/common/frequencyA/dopplerBandwidth
Type: Float64	Shape: scalar
Description: Common Doppler Bandwidth u	used for processing interferogram
units	Hz
/science/LSAR/GOFF/metadata/processin	ngInformation/parameters/pixelOffsets/frequencyA/rangeBandwidth
Type: Float64	Shape: scalar
Description: Processed slant range bandwi	dth for frequencyA pixel offsets layers
units	Hz
/science/LSAR/GOFF/metadata/processir	gInformation/parameters/pixelOffsets/frequencyA/azimuthBandwidth

Type: Float64	Shape: scalar
Description: Processed azimuth bandy	width for frequencyA pixel offsets layers
units	Hz
/science/LSAR/GOFF/metadata/proce ampling	assingInformation/parameters/pixelOffsets/frequencyA/correlationSurfaceOvers
Type: UInt32	Shape: scalar
<b>Description:</b> Oversampling factor of th	e cross-correlation surface
units	unitless
/science/LSAR/GOFF/metadata/proce	essingInformation/parameters/pixelOffsets/frequencyA/margin
Type: UInt32	Shape: scalar
<b>Description:</b> Margin in pixels around re	eference RSLC edges excluded during cross-correlation computation
units	unitless
/science/LSAR/GOFF/metadata/proce	essingInformation/parameters/pixelOffsets/frequencyA/slantRangeStartPixel
Type: UInt32	Shape: scalar
<b>Description:</b> Reference RSLC start pix	cel in slant range
units	unitless
/science/LSAR/GOFF/metadata/proce	essingInformation/parameters/pixelOffsets/frequencyA/alongTrackStartPixel
Type: UInt32	Shape: scalar
Description: Reference RSLC start pix	el in along-track
units	unitless
/science/LSAR/GOFF/metadata/proce	essingInformation/parameters/pixelOffsets/frequencyA/slantRangeSkipWindowS
Type: Illnt32	Shape: scalar
Description: Slant range cross-correla	tion skip window size in pixels
units	unitless
/science/LSAR/GOFF/metadata/proce	essingInformation/parameters/pixelOffsets/frequencyA/alongTrackSkipWindowS
Type: UInt32	Shape: scalar
Description: Along-track cross-correlat	tion skip window size in pixels
units	unitless
/science/LSAR/GOFF/metadata/proce wSize	essingInformation/parameters/pixelOffsets/frequencyA/layer1/alongTrackWindo
Type: UInt32	Shape: scalar
Description: Along-track cross-correlat	tion window size in pixels
units	unitless
/science/LSAR/GOFF/metadata/proce	essingInformation/parameters/pixelOffsets/frequencyA/layer1/slantRangeWindo
Type: UInt32	Shape: scalar
Description: Slant range cross-correla	tion window size in pixels
units	unitless
/science/LSAR/GOFF/metadata/proce	essingInformation/parameters/pixelOffsets/frequencyA/layer1/alongTrackSearch
Type: Ulnt32	Shape: scalar
Description: Along-track cross-correlat	tion search window size in pixels

VindowSize	adata/processinginformation/parameters/pixeiOffsets/frequencyA/layer1/siantRangeSearch
Type: UInt32	Shape: scalar
Description: lant range cro	ss-correlation search window size in pixels
units	unitless
/science/LSAR/GOFF/met wSize	adata/processingInformation/parameters/pixelOffsets/frequencyA/layer2/alongTrackWindo
Type: UInt32	Shape: scalar
Description: Along-track cr	oss-correlation window size in pixels
units	unitless
/science/LSAR/GOFF/met wSize	adata/processingInformation/parameters/pixelOffsets/frequencyA/layer2/slantRangeWindo
Type: UInt32	Shape: scalar
Description: Slant range c	oss-correlation window size in pixels
units	unitless
/science/LSAR/GOFF/met WindowSize	adata/processingInformation/parameters/pixelOffsets/frequencyA/layer2/alongTrackSearch
Type: UInt32	Shape: scalar
Description: Along-track cr	oss-correlation search window size in pixels
units	unitless
/science/LSAR/GOFF/met WindowSize	adata/processingInformation/parameters/pixelOffsets/frequencyA/layer2/slantRangeSearch
Type: UInt32	Shape: scalar
Description: Slant range c	oss-correlation search window size in pixels
units	unitless
/science/LSAR/GOFF/met wSize	adata/processingInformation/parameters/pixelOffsets/frequencyA/layer3/alongTrackWindo
Type: UInt32	Shape: scalar
Description: Along-track cr	oss-correlation window size in pixels
units	unitless
/science/LSAR/GOFF/met wSize	adata/processingInformation/parameters/pixelOffsets/frequencyA/layer3/slantRangeWindo
Type: UInt32	Shape: scalar
Description: Slant range c	oss-correlation window size in pixels
units	unitless
/science/LSAR/GOFF/met WindowSize	adata/processingInformation/parameters/pixelOffsets/frequencyA/layer3/alongTrackSearch
Type: UInt32	Shape: scalar
Description: Along-track cr	oss-correlation search window size in pixels
units	unitless
/science/LSAR/GOFF/met WindowSize	adata/processingInformation/parameters/pixelOffsets/frequencyA/layer3/slantRangeSearch
Type: UInt32	Shape: scalar
Description: Slant range c	oss-correlation search window size in pixels

units	Unitiess
Type, etring	gimormation/parameters/geocoding/rangeionosphericcorrectionApplied
Type. String	Shape. Scalar
Description: Flag to indicate if the range for	iospheric correction is applied to improve geolocation
/science/LSAR/GOFF/metadata/processin	gInformation/parameters/geocoding/azimuthIonosphericCorrectionApplied
Type: string	Shape: scalar
<b>Description:</b> Flag to indicate if the azimuth	ionospheric correction is applied to improve geolocation
/science/LSAR/GOFF/metadata/processin plied	gInformation/parameters/geocoding/hydrostaticTroposphericCorrectionAp
Type: string	Shape: scalar
Description: Flag to indicate if hydrostatic to	ropospheric correction is applied to improve geolocation
/science/LSAR/GOFF/metadata/processin	gInformation/parameters/geocoding/wetTroposphericCorrectionApplied
Type: string	Shape: scalar
Description: Flag to indicate if wet troposph	neric correction is applied to improve geolocation
/science/LSAR/GOFF/metadata/processin	gInformation/algorithms/softwareVersion
Type: string	Shape: scalar
Description: Software version used for proc	pessing
/science/LSAR/GOFF/metadata/processin	gInformation/algorithms/geocoding/complexGeocodingInterpolation
Type: string	Shape: scalar
Description: Geocoding interpolation algori	thm for complex-valued datasets
algorithm_type	Geocoding
/science/LSAR/GOFF/metadata/processin	gInformation/algorithms/geocoding/integerGeocodingInterpolation
Type: string	Shape: scalar
Description: Geocoding interpolation algorit	thm for integer datasets
algorithm type	Geocoding
/science/LSAR/GOFF/metadata/processin	glnformation/algorithms/geocoding/floatingGeocodingInterpolation
Type: string	Shape: scalar
Description: Geocoding interpolation algorit	thm for floating point datasets
algorithm type	Geocoding
/science/LSAR/GOFF/metadata/processin	gInformation/algorithms/geocoding/demInterpolation
Type: string	Shape: scalar
Description: DEM interpolation algorithm	
algorithm type	Geocoding
/science/LSAR/GOFF/metadata/processin	glnformation/algorithms/coregistration/coregistrationMethod
Type: string	Shape: scalar
Description: RSLC coregistration method	
algorithm type	RSLC coregistration
/science/LSAR/GOFF/metadata/processin	gInformation/algorithms/coregistration/geometryCoregistration
Type: string	Shape: scalar
Description: Geometry coregistration algori	thm
algorithm type	RSLC coregistration
/science/LSAR/GOFF/metadata/processin	gInformation/algorithms/coregistration/resampling

Type: string	Shape: scalar
Description: Secondary RSLC resampling a	algorithm
algorithm_type	RSLC coregistration
/science/LSAR/GOFF/metadata/processin	gInformation/algorithms/crossCorrelation/layer1/crossCorrelationAlgorithm
Type: string	Shape: scalar
Description: Cross-correlation algorithm for	layer 1
algorithm_type	RSLC coregistration
/science/LSAR/GOFF/metadata/processin	gInformation/algorithms/crossCorrelation/layer2/crossCorrelationAlgorithm
Type: string	Shape: scalar
<b>Description:</b> Cross-correlation algorithm for	layer 2
algorithm_type	RSLC coregistration
/science/LSAR/GOFF/metadata/processin	gInformation/algorithms/crossCorrelation/layer3/crossCorrelationAlgorithm
Type: string	Shape: scalar
Description: Cross-correlation algorithm for	layer 3
algorithm_type	RSLC coregistration
/science/LSAR/GOFF/metadata/processin	gInformation/inputs/I1ReferenceSIcGranules
Type: string	Shape: (numberOfInputL1Files)
Description: List of input reference L1 RSL0	C products used
/science/LSAR/GOFF/metadata/processin	gInformation/inputs/I1SecondarySIcGranules
Type: string	Shape: (numberOfInputL1Files)
Description: List of input secondary L1 RSL	.C products used
/science/LSAR/GOFF/metadata/processin	gInformation/inputs/orbitFiles
Type: string	Shape: (numberOfInputOrbitFiles)
Description: List of input orbit files used	
/science/LSAR/GOFF/metadata/processin	gInformation/inputs/configFiles
Type: string	Shape: (numberOfInputConfigFiles)
Description: List of input config files used	
/science/LSAR/GOFF/metadata/processin	gInformation/inputs/demSource
Type: string	Shape: scalar
Description: Description of the input digital	elevation model (DEM)

### 5.5 Other Radar Metadata

#### Table 5-5 NISAR HDF5 variables related to useful radar metadata

Radar metadata-related variab	les
/science/LSAR/GOFF/metadata/orbit	/time
Type: Float64	Shape: (orbitListLength)
Description: Time vector record. This	record contains the
time corresponding to p	osition, velocity, acceleration records
units	seconds since YYYY-MM-DD HH:MM:SS
/science/LSAR/GOFF/metadata/orbit	position
Type: Float64	Shape: (orbitListLength, tripletxyz)
Description: Position vector record. If	his record contains the platform position data
with respect to WGS84	G1762 reference frame
unito	meters
Type: Elost64	Shane: (orbitl jetl ength tripletyyz)
Description: Valacity vector record Th	bic record contains the platform
velocity data with respect	to WGS84 G1762 reference frame
units	meters per second
/science/LSAR/GOFF/metadata/orbit	
Type: Float64	Shape: (orbitListLength, tripletxyz)
Description: Acceleration vector record	d. This record contains the
platform acceleration da	ta with respect to WGS84 G1762 reference frame
·	
units	meters per second squared
/science/LSAR/GOFF/metadata/orbit	/orbitType
Type: string	Shape: scalar
Description: PrOE (or) NOE (or) MOE	(or) POE (or) Custom
/science/LSAR/GOFF/metadata/attitu	de/time
Type: Float64	Shape: (orbitListLength)
Description: Time vector record. This	record contains the
time corresponding to a	titude and quaternion records
	seconds since YYYY-MM-DD HH:MM:SS
	(de/quaternions
Type: Floato4	at a 2 a 2)
<b>Description:</b> Attitude quaternions (qu,	q 1, q2, q3)
units	unitless
/science/LSAR/GOFF/metadata/attitu	de/angularVelocity
Type: Float64	Shape: (attitudeListLength, tripletxyz)
Description: Attitude angular velocity	vectors (wx, wy, wz)
units	radians per second
/science/LSAR/GOFF/metadata/attitu	de/eulerAngles

Type: Float64	Shape: (attitudeListLength, tripletxyz)
Description: Attitude Euler angles (roll,	, pitch, yaw)
units	degrees
/science/LSAR/GOFF/metadata/attitu	de/attitudeType
Type: string	Shape: scalar
Description: PrOE (or) NOE (or) MOE	(or) POE (or) Custom

## 5.6 Radar Grid

#### Table 5-6 NISAR HDF5 variables related to metadata cube

Metadata cube-related variable	es	
/science/LSAR/GOFF/metadata/rada	Grid/sla	antRange
Type: Float64	Shape	e: (radarCubeHeight, radarCubeLength, radarCubeWidth)
Description: Slant range in meters		
_FillValue		nan
grid_mapping		projection
long_name		Slant-range
units		meters
/science/LSAR/GOFF/metadata/rada	Grid/ze	roDopplerAzimuthTime
Type: Float64	Shape	e: (radarCubeHeight, radarCubeLength, radarCubeWidth)
Description: Zero doppler azimuth time	e in seco	onds
units		seconds since YYYY-mm-dd HH:MM:SS
/science/LSAR/GOFF/metadata/rada	Grid/ep	sg
Type: Int32	Shape	e: scalar
Description: EPSG code correspondin	g to the	coordinate system used for representing the geolocation grid
long_name		EPSG code
units		unitless
/science/LSAR/GOFF/metadata/rada	Grid/xC	Coordinates
Type: Float64	Shape	e: (radarCubeWidth)
Description: X coordinate values corre	espondin	ig to the radar grid
long_name		X coordinate of projection
standard_name		projection_x_coordinate
units		meters
/science/LSAR/GOFF/metadata/rada	Grid/yC	Coordinates
Type: Float64	Shape	e: (radarCubeWidth)
Description: Y coordinate values corre	espondin	ig to the radar grid
long_name		Y coordinate of projection
standard_name		projection_y_coordinate
units		meters
/science/LSAR/GOFF/metadata/rada	Grid/in	cidenceAngle
Type: Float32	Shape	e: (radarCubeHeight, radarCubeLength, radarCubeWidth)
<b>Description:</b> Incidence angle is defined height	d as the	angle between the LOS vector and the normal to the ellipsoid at the target
max		90.0
min		0.0
_FillValue		nan
grid_mapping		projection
long_name		Incidence angle
units		degrees
/science/LSAR/GOFF/metadata/rada	Grid/los	sUnitVectorX

Type: Float32	Shape	: (radarCubeHeight, radarCubeLength, radarCubeWidth)
Description: East component of unit v	ector of L	OS from target to sensor
max		-1.0
min		1.0
_FillValue		nan
grid_mapping		projection
long_name		LOS unit vector X
units		unitless
/science/LSAR/GOFF/metadata/rada	rGrid/los	sUnitVectorY
Type: Float32	Shape	: (radarCubeHeight, radarCubeLength, radarCubeWidth)
Description: North component of unit	vector of	LOS from target to sensor
max		-1.0
min		1.0
_FillValue		nan
grid_mapping		projection
long_name		LOS unit vector Y
units		unitless
/science/LSAR/GOFF/metadata/rada	rGrid/alo	ongTrackUnitVectorX
Type: Float32	Shape	: (radarCubeHeight, radarCubeLength, radarCubeWidth)
Description: East component of unit v	ector alo	ng ground track
max		-1.0
min		1.0
_FillValue		nan
grid_mapping		projection
long_name		Along-track unit vector X
units		unitless
/science/LSAR/GOFF/metadata/rada	rGrid/alo	ongTrackUnitVectorY
Type: Float32	Shape	: (radarCubeHeight, radarCubeLength, radarCubeWidth)
Description: North component of unit	vector alo	ong ground track
max		-1.0
min		1.0
_FillValue		nan
grid_mapping		projection
long_name		Along-track unit vector Y
units		unitless
/science/LSAR/GOFF/metadata/rada	rGrid/ele	evationAngle
Type: Float32	Shape	: (radarCubeHeight, radarCubeLength, radarCubeWidth)
Description: Elevation angle is defined	d as the a	angle between the LOS vector and the normal to the ellipsoid at the
sensor		
max		90.0
min		0.0
_FillValue		nan
grid_mapping		projection
long_name		Elevation angle
units		degrees
/science/LSAR/GOFF/metadata/rada	rGrid/gro	oundTrackVelocity
Type: Float64	Shape	: (radarCubeLength, radarCubeWidth)

Description: Absolute value of the plat	form velocity scaled at the target height
FillValue	nan
	Ground-track velocity
	meters per second
/science/LSAP/GOEE/metadata/radar	Grid/secondaruZeroDonnlerTime
Type: Float64	Shape: (radarCubeHeight radarCubeLength radarCubeWidth)
<b>Description:</b> Zero Doppler azimuth time	e of corresponding nixel in
secondary image	
units	seconds since yyyy-mm-dd
/science/LSAR/GOFF/metadata/radar	Grid/secondarySlantRange
Type: Float64	Shape: (radarCubeHeight, radarCubeLength, radarCubeWidth)
<b>Description:</b> Slant range of correspond	ling pixel in secondary image
units	meters
/science/LSAR/GOFF/metadata/radar	Grid/parallelBaseline
Type: Float64	Shape: (radarCubeWidth, radarCubeLength, twoLayersCubeHeight)
Description: Parallel component of the	InSAR baseline
units	meters
/science/LSAR/GOFF/metadata/radar	Grid/perpendicularBaseline
Type: Float64	Shape: (radarCubeWidth, radarCubeLength, twoLaversCubeHeight)
Description: Perpendicular component	of the InSAR baseline
units	meters
/science/LSAR/GOFF/metadata/radar	Grid/projection
Type: Int32	Shape: scalar
Description: Product map grid projection	on: EPSG code, with additional projection information as HDF5 Attributes
ellipsoid	Projection ellipsoid
epsg_code	Projection EPSG code
false_easting	The value added to all abscissa values in the rectangular coordinates for a map projection
false_northing	The value added to all ordinate values in the rectangular coordinates for a map projection
arid mapping name	Grid manning variable name
inverse flattening	Inverse flattening of the ellipsoidal figure
latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map
longitude_of_projection_origi	n The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum
semi maior axis	Semi-maior axis
spatial ref	Spatial reference
utm zone number	UTM zone number
/science/LSAR/GOFF/metadata/radar	Grid/heightAboveEllipsoid
Type: Float64	Shape: (radarCubeHeight)
Description: Height values above WGS	S84 Ellipsoid corresponding to the radar grid
standard name	height above reference ellipsoid
units	meters

### 6 METADATA CUBE

In this section, we provide an overview of the metadata cubes used to store spatially-varying ancillary data in the secondary layers of the NISAR L-SAR product HDF5 granules. Note that this sparse representation is to assist users in ingesting and analyzing NISAR products within existing GIS software and is not meant to replace traditional representations of SAR data within the product granules or traditional processing approaches with radar geometry-aware software.

Metadata cubes are represented as three-dimensional arrays in the NISAR product HDF5 modules (Figure 6-1). The axes of the array are interpreted as (height, increasing azimuth time, and increasing slant range) in case of radar geometry products and as (height, decreasing northing, and increasing easting) in case of geocoded products. The data is organized with height as the first axis, as this allows one to directly ingest data as GCPs or rasters into existing GIS software. Each height layer is the same size. Metadata cubes will have fixed grid spacing (3 km in azimuth/northing x 1 km in slant range/easting x 1.5 km in height and will allow for easy merging when multiple products along the same imaging track are to be concatenated. The metadata fields on this coarse resolution grid will be evaluated using traditional radar processing approaches without approximations. The metadata cube will also span a field slightly larger than the original image product to allow users to interpolate data without introducing edge effects. Such low-resolution representation of slowly varying parameters has been demonstrated for InSAR products and processing **Error! Reference source not found.**.



Figure 6-1. Metadata cube layer schematic

## 6.1 Metadata Cube Interpolation Example

We provide here a conceptual example of how these metadata cubes can be used within an existing GIS framework. Let us consider a GUNW product on a UTM Zone 10 grid (Table 6-1).

We use a geocoded product for the demonstration but the presented approach can be easily extended to radar coordinate products by replacing northing axis by azimuth time and easting axis by slant range.

Name	Value	Description
Primary la	yer properties	
xmin	100000.0	Easting of the first column (m)
xmax	340000.0	Easting of the last column (m)
dx	30.0	Column spacing in Easting (m)
Nx	8001	Number of columns
ymax	570000.0	Northing of first row (m)
ymin	330000.0	Northing of last row (m)
dy	-30.0	Row spacing in Northing (m). Negative to emphasize North-up imagery in geocoded products
Ny	8001	Number of rows
Metadata	cube properties	
Cxmin	97000.0	Easting of first column (m)
Cxmax	343000.0	Easting of last column (m)
Cdx	1000.0	Column spacing in Easting (m)
CNx	247	Number of columns
Cymax	579000.0	Northing of first row (m)
Cymin	321000.0	Northing of last row(m)
Cdy	-3000.0	Row spacing in Northing (m). Negative to emphasize North-up imagery in geocoded products
CNy	87	Number of rows
Czmin	-1500	Height of the first layer (m)
Czmax	9000	Height of the last layer (m)
Cdz	1500	Layer spacing in height (m)
CNz	8	Number of height layers

|--|

Suppose we are interested in computing the Perpendicular Baseline (Bperp) at a pixel of interest located at UTM coordinates point (Px,Py). Since these are coordinates on a map domain, we can look up a DEM to get the height at this point. The three-dimensional point of interest then becomes (Px, Py, h(Px,Py)).

The metadata cube for Perpendicular baseline can be thought of as a three-dimensional field Bperp(x,y,z) – even though it is oriented as (Nz,Ny,Nx) in the HDF5 file for ease of use with a GIS. The user can use standard built-in regular grid three-dimensional interpolation routines in languages like MATLAB (e.g, interp3), IDL or Python (e.g, RegularGridInterpolator) to interpolate the Bperp array. We recommend cubic interpolation for best results. If a three-dimensional interpolator is not available, one could use two-dimensional cubic interpolation for each height layer followed by a one-dimensional cubic interpolation in the following manner:

1. Populate f(i), i=0,...Nz-1 by two-dimensional cubic interpolation of each height layer:

$$f(i) = Bperp\left[i, \frac{Py - Cymax}{Cdy}, \frac{Px - Cxmax}{Cdx}\right]$$

where the numbers in the square brackets indicate indices into the three-dimensional cube. For example, if we are interested in the point (107590.0 East, 555870.0 North, 300.0 Height), we would interpolate at Row 7.71 and Column 10.59 for each height layer.

2. Interpolate f(i) using one-dimensional cubic interpolation:

$$Bperp(Px, Py, h(Px, Py)) = f\left[\frac{h(Px, Py) - Czmin}{Cdz}\right]$$

where the number in the square bracket indicates an index into a one-dimensional array. For example, for a height value of 200.0, we would interpolate at an index of 1.2.

#### 6.2 Metadata Cube Usage Note

Note that the metadata cubes are designed to accommodate one double-precision cube within 1 MB of memory, allowing for information to be easily stored in memory for on-the-fly computation within GIS frameworks or software without much overhead. The metadata cubes are not a replacement for traditional SAR processing approaches or very high-resolution analyses. They are meant to facilitate rapid processing and analysis by non-experts and will serve the needs for most SAR applications. Analyses show that the geolocation error is on the order of 1.5 cm due to interpolation which is significantly smaller than errors from sources such as DEM, orbits, and atmospheric path delay. Interpolation errors for each of the metadata layers will be reported after additional study.

## **APPENDIX A: ACRONYMS**

ADT	Algorithm Development Team
AT	Along Track
AWS	Amazon Web Services
BFPQ	Block adaptive Floating-Point Quantization
Cal/Val	Calibration and Validation (also sometimes cal/val)
CDR	Critical Design Review
CF	Climate and Forecast
CPU	Central Processing Unit
CRSD	Calibration Raw Signal Data
CSV	Comma-separated values
DAAC	Distributed Active Archive Center
DEM	Digital Elevation Model
DN	Digital Number
EAR	Export Administration Regulations
ECMWF	European Centre for Medium-Range Weather Forecasts
ECEF	Earth Centered Earth Fixed
EPSG	European Petroleum Survey Group
ESA	European Space Agency
FM	Frequency Modulation
FOP	Forecast Orbit Ephemeris
FOV	Field of View
GCOV	Geocoded Polarimetric Covariance (L2_GCOV)
GCP	Ground Control Point
GDAL	Geospatial Data Abstraction Library
GDS	Ground Data System
GIS	Geographic Information System
GMTED	Global Multi-resolution Terrain Elevation Data
GOFF	Geocoded Pixel Offsets (L2_GOFF)
GPU	Graphics Processing Unit
GSLC	Geocoded Single Look Complex (L2_GSLC)
GUNW	Geocoded Unwrapped Interferogram (L2_GUNW)
НК, НКТМ	Housekeeping Telemetry
HDF5	Hierarchical Data Format version 5
InSAR	Interferometric Synthetic Aperture Radar
ISCE	InSAR Scientific Computing Environment
ISCE3	InSAR Scientific Computing Environment Enhanced Edition (for NISAR)
ISO	International Organization for Standardization

ISRO	Indian Space Research Organisation (British spelling)
L0B	Level-0B (data)
L1	Level-1 (data)
L2	Level-2 (data)
LOS	Line-Of-Sight
LUT	Lookup Table
Mbps	Megabits per second
MHz	Megahertz
MOE	Medium-precision Orbit Ephemeris
NCSA	National Center for Supercomputing Applications
NetCDF4	Network Common Data Form version 4
NISAR	NASA-ISRO Synthetic Aperture Radar
NOE	Near-Realtime Orbit Ephemeris
PDR	Preliminary Design Review
POD	Precision Orbit Determination
POE	Precision Orbit Ephemeris
PRF	Pulse Repetition Frequency
QA	Quality Assurance
REE	Radar Echo Emulator
RFI	Radio Frequency Interference
RIFG	Range-Doppler Interferogram (L1_RIFG)
ROFF	Range-Doppler Pixel Offsets (L1_ROFF)
RRSD	Radar Raw Signal Data
RRST	Radar Raw Science Telemetry
RSLC	Range-Doppler Single Look Complex (L1_RSLC)
RUNW	Range-Doppler UnWrapped Interferogram (L1_RUNW)
SAR	Synthetic Aperture Radar
SAS	Science Algorithm Software
SDS	Science Data System
SDT	Science Definition Team
SIS	Software Interface Specification
SLC	Single Look Complex
SNAPHU	Statistical-cost, Network-flow Algorithm for Phase Unwrapping
SRTM	Shuttle Radar Topography Mission
ST	Science Team
TAI	International Atomic Time (Temps Atomique International)
TCF	Terrain Correction Factor
TEC	Total Electron Content
TFdb	Track-frame Database
SWST	Sampling Window Start Time
UR	Urgent Response

UTC	Universal Time Coordinated
UTM	Universal Transverse Mercator
WGS84	World Geodetic System 84
XML	eXtensible Markup Language (xml in code)
YAML	YAML Ain't Markup Language

## **APPENDIX B: GEOCODED PRODUCT GRIDS**

NISAR L2 products will be generated on a pre-defined Track/Frame system. The projection system for a particular frame will be available to the users as a predefined map and will be held constant through the life of the system. Each L2 HDF5 granule itself will include information indicating the projection used for the product.

### Map Projections

The NISAR SDS is able to ingest any Digital Elevation Model whose vertical datum represents height above the WGS84 Ellipsoid and the horizontal datum can be represented by a European Petroleum Standards Group (EPSG) code for generating geocoded product. Table 7-1 lists the various projection systems used to output L2 geocoded products.

EPSG code	PROJ.4 string	Common Name	Geographical scope
3031	+proj=stere +lat_0=-90 +lat_ts=-71 +lon_0=0 +k=1 +x_0=0 +y_0=0 +datum=WGS84 +units=m +no_defs	Antarctic Polar Stereographic	Antarctica and Southern Hemisphere Sea Ice
3413	+proj=stere +lat_0=90 +lat_ts=70 +lon_0=- 45 +k=1 +x_0=0 +y_0=0 +datum=WGS84 +units=m +no_defs	NSIDC Sea Ice Polar Stereographic North	Greenland and Northern Hemisphere Sea Ice
32601- 32660	+proj=utm +zone=X-32600 +datum=WGS84 +units=m +no_defs	UTM Zone North	Northern Hemisphere Land except Greenland
32701- 32760	+proj=utm +zone=X-32700 +south +datum=WGS84 +units=m +no_defs	UTM Zone South	Southern Hemisphere Land except Antarctica

#### Table B-1. Projection Systems for NISAR L2 Products

## **Grid Alignment**

NISAR L2 products will use a "pixel is area" convention

(http://geotiff.maptools.org/spec/geotiff2.5.html, "The "PixelIsArea" raster grid space R, which is the default, uses coordinates I and J, with (0,0) denoting the upper-left corner of the image, and increasing I to the right, increasing J down. The first pixel-value fills the square grid cell with the bounds: top-left = (0,0), bottom-right = (1,1)").